

Strategies for achieving sub-10fs timing in large-scale FELs

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LCLS

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MENLO SYSTEMS

FEL 2012

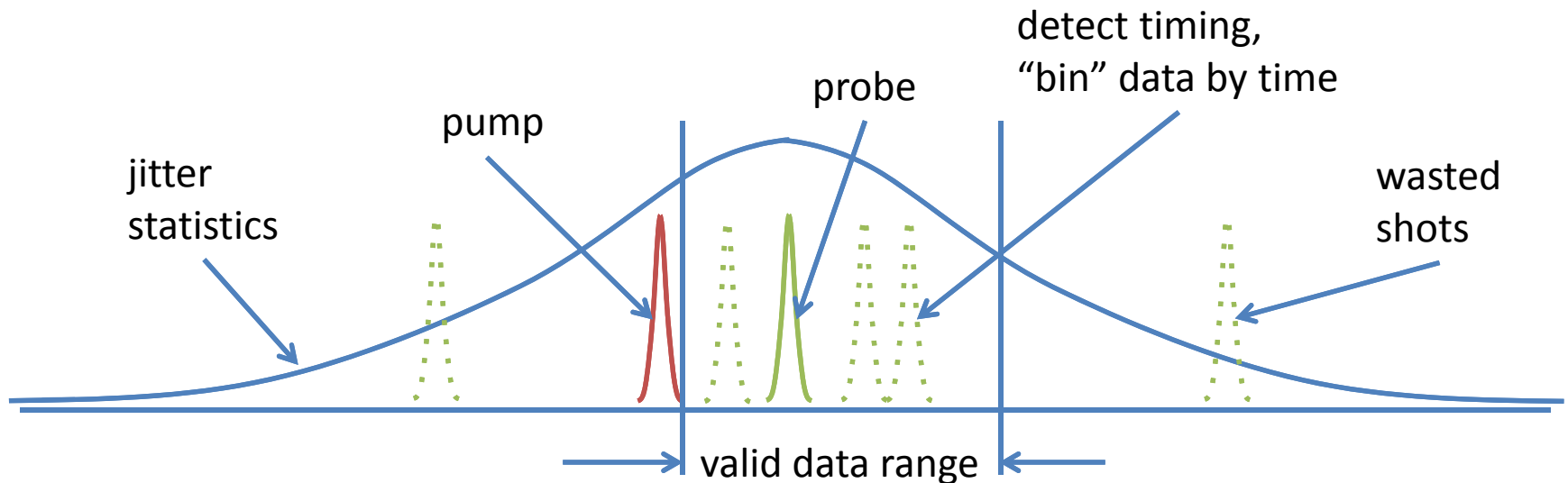
NARA, JAPAN

Outline

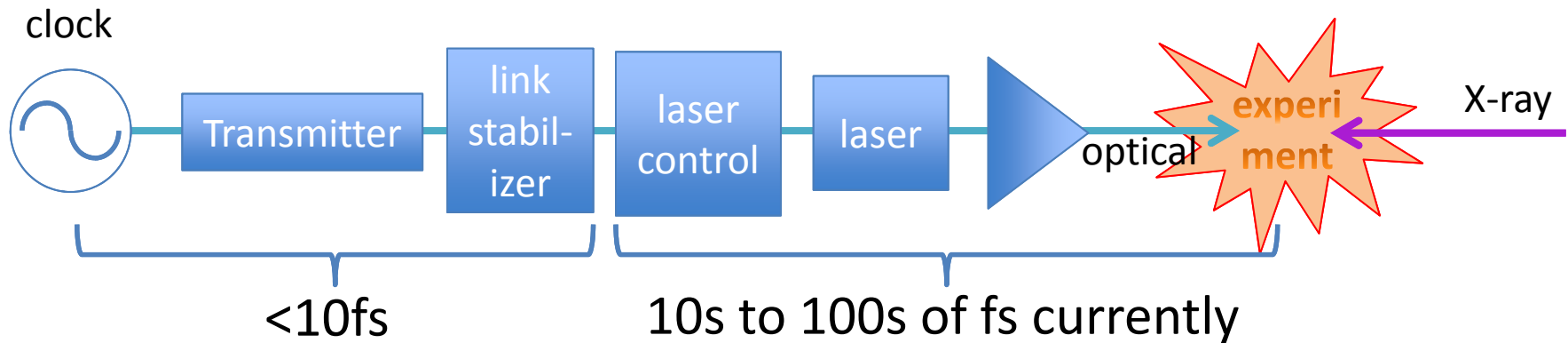
- Overall system design approach for $<10\text{fs}$
- Subsystems
 - Clock requirements
 - Stabilized link
 - Laser oscillator timing control
 - Downstream monitors and feedback
- Conclusions

<10fs pump/probe experiments drive timing requirements

- $\leq 10\text{fs}$ photon pulses from LCLS, SACLA, FLASH...
- Want timing uncertainty $\leq$ pulse width, otherwise...
 - Pulse is statistically widened
 - Timing range is statistically sampled (then “binned” if measured)
 - Shots are wasted, reducing effective repute

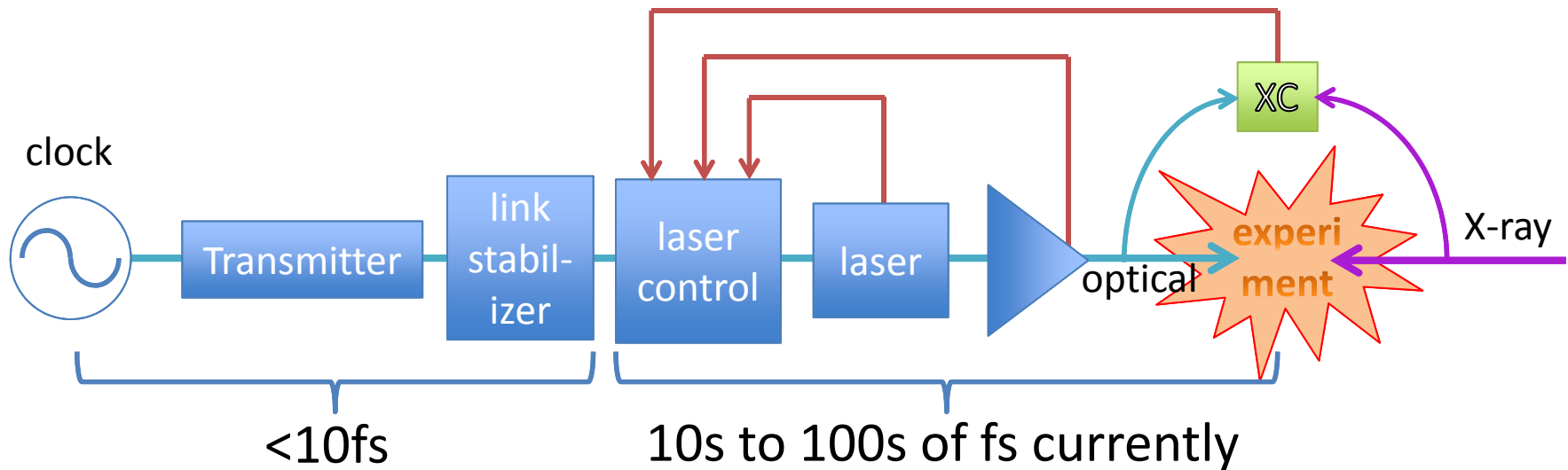


Laser synchronization path



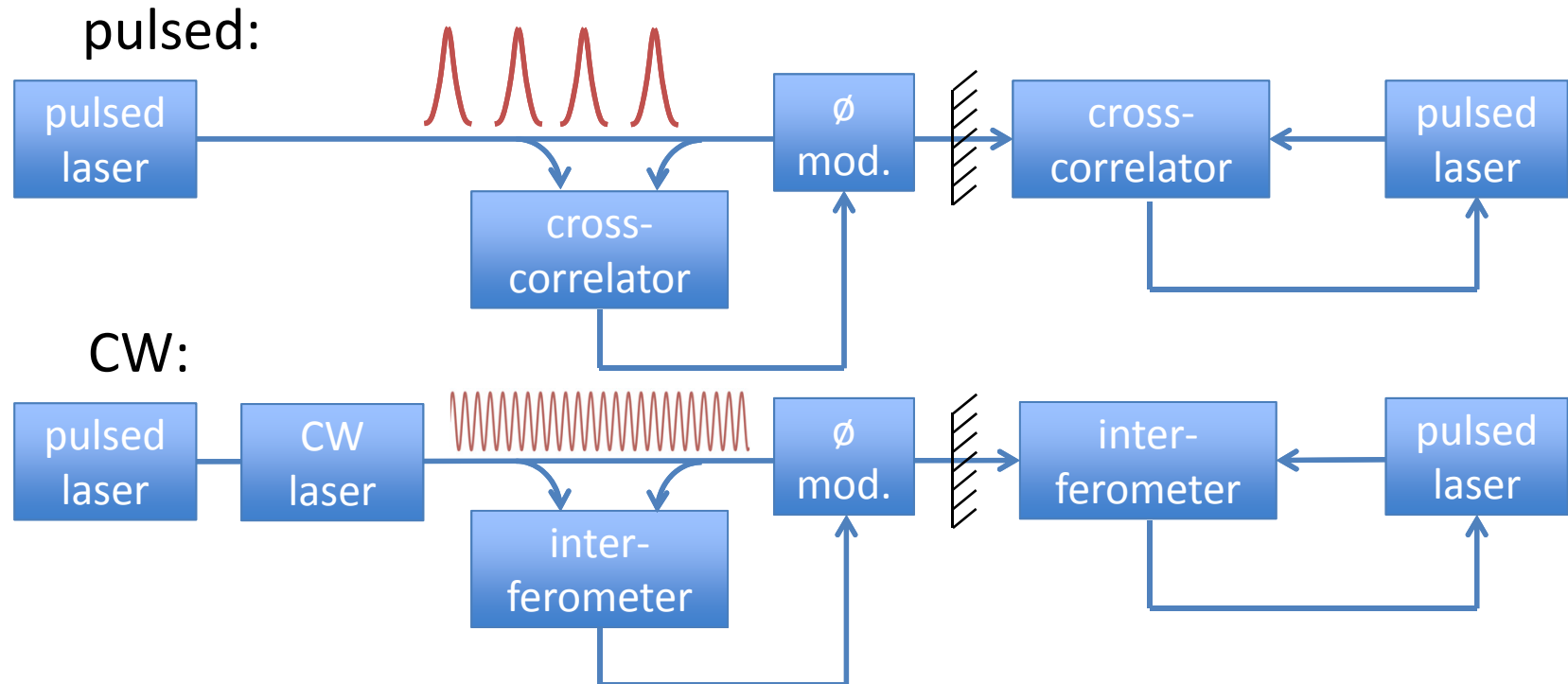
- Carry stability of clock down stream
 - Minimize jitter added by subsystems

Laser synchronization path



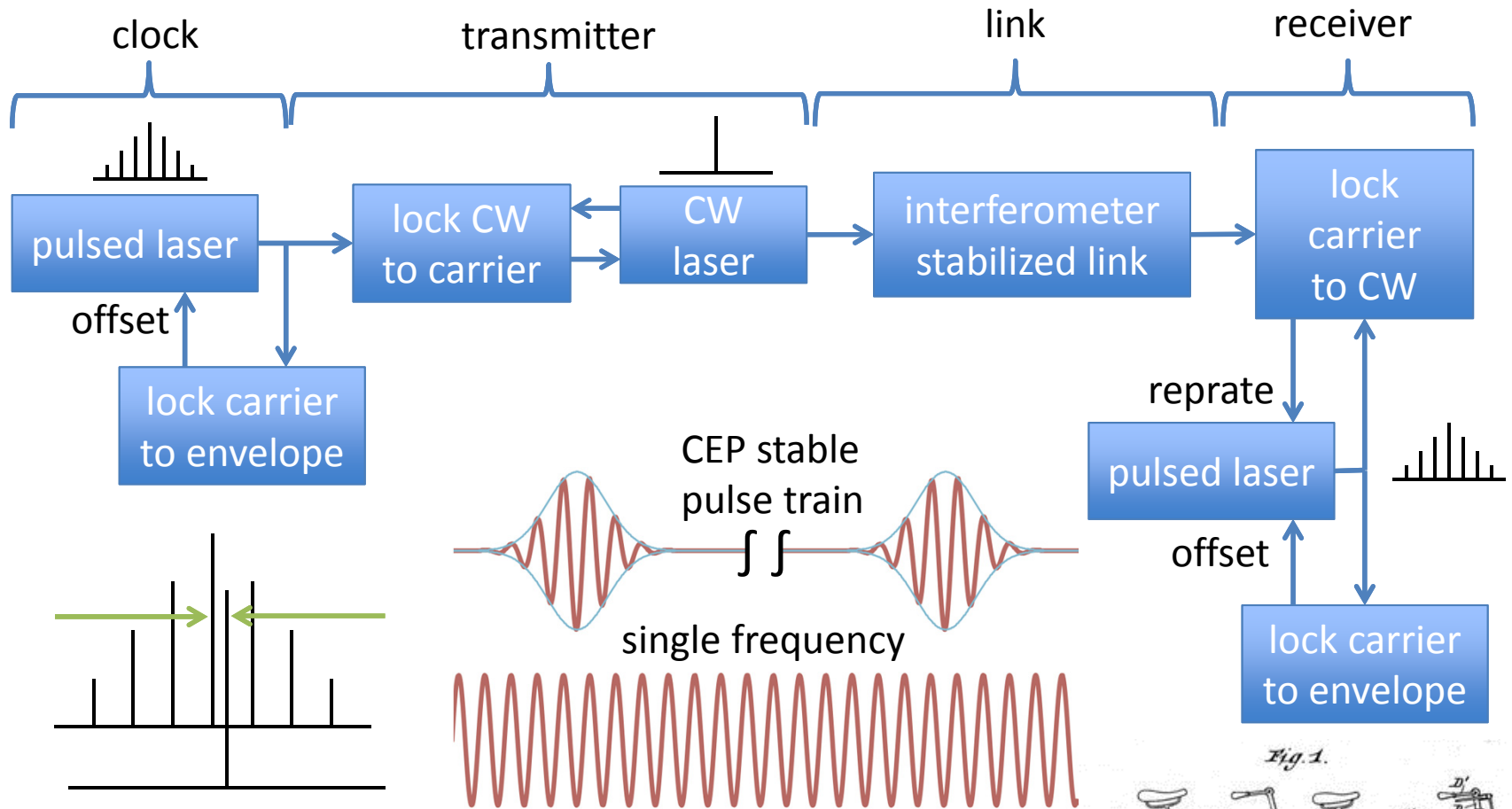
- Carry stability of clock down stream
 - Minimize jitter added by subsystems
 - Feedback at maximum bandwidth for each stage
- X-ray jitter assumed to be low (Byrd et al, TUPD29)

Clock distribution methods

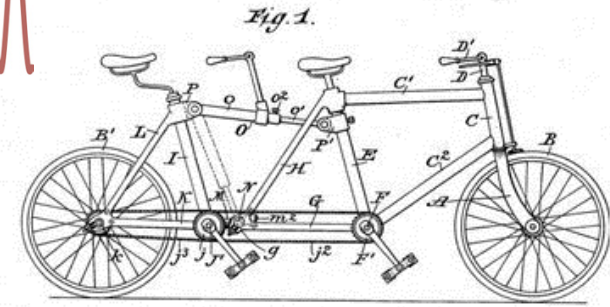


- CW carrier : continuous signal (fringe counting), no fiber nonlinearity
 - Analogous to RF clock, but 10^6 higher frequency
 - $\Delta t = \Delta \phi / 2\pi f = 1 \text{ rad} / (2\pi \cdot 200 \text{ THz}) = 0.8 \text{ fs}$

Linking CW and pulsed lasers



- Timing always transferred via optical phase detection



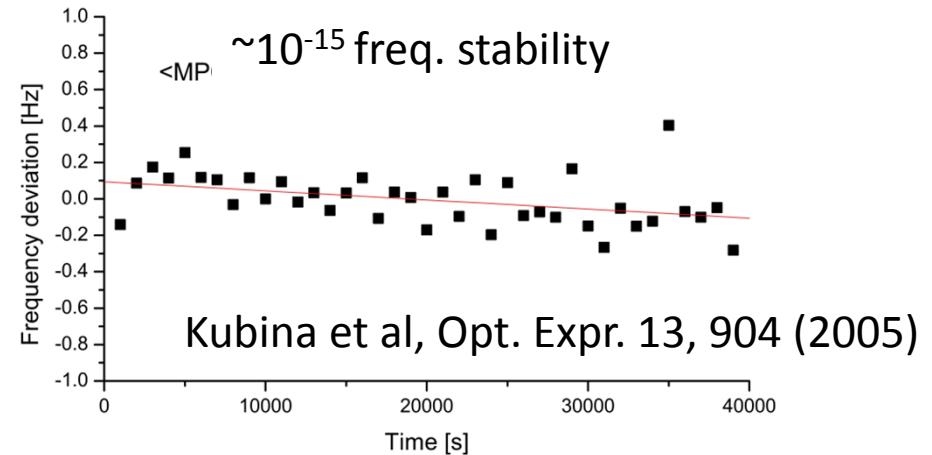
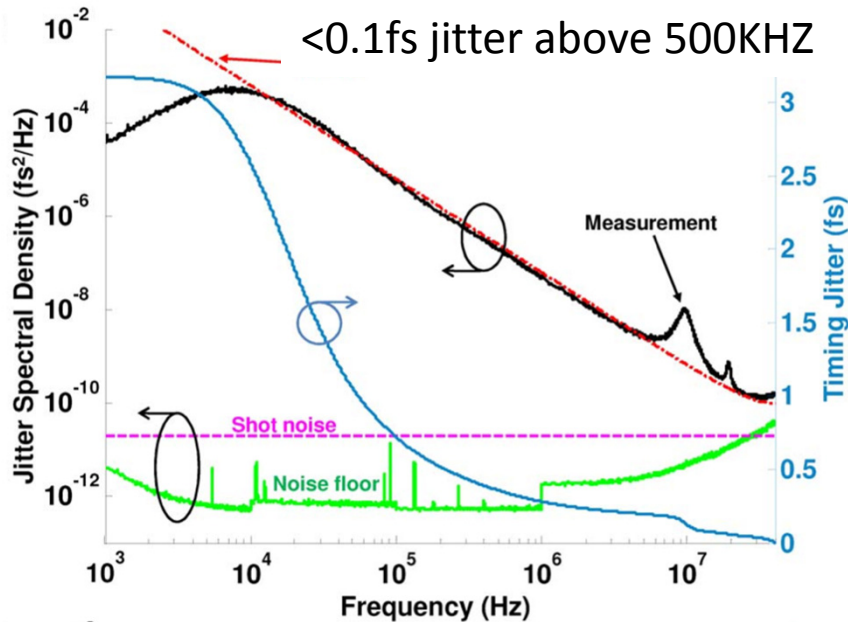
Clock and distribution via links

How good does the clock have to be?



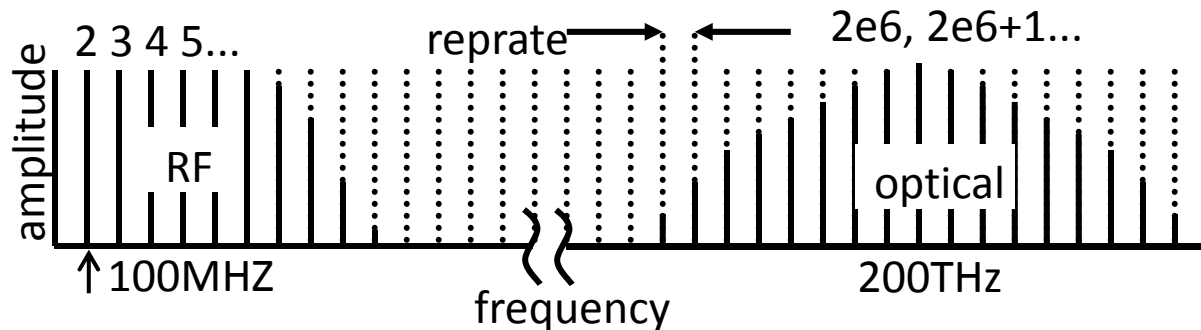
- Determined by delay difference $t_D = t_A - t_B$
- High frequency: differential noise with period $< 2t_D$
- Low frequency: phase delay change $\Delta t = t_D \frac{\Delta f}{f}$
- Example: 200m fiber
 - t_D is $1\mu\text{s}$
 - High frequency noise above $500\text{kHz} < 1\text{fs}$
 - Long term frequency drift $< 10^{-9}$

Optical clocks are good enough



J. A. Cox et al, Opt. Lett. 35, 3522 (2010)

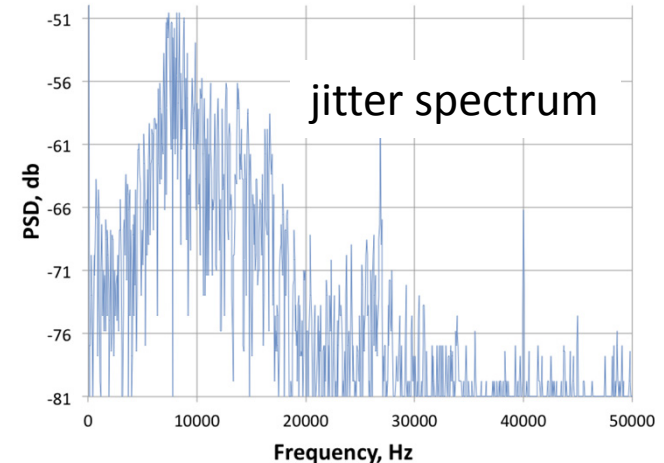
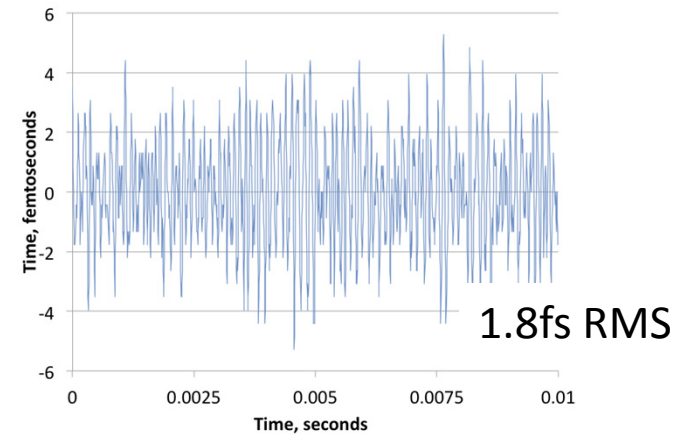
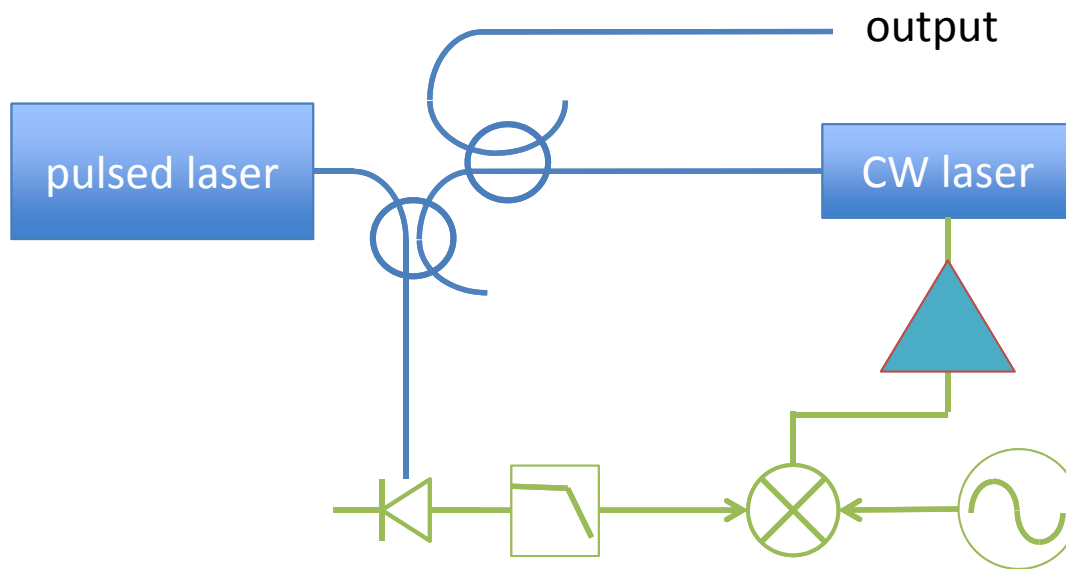
- RF and optical frequencies, at exact integer multiples



Menlo Systems

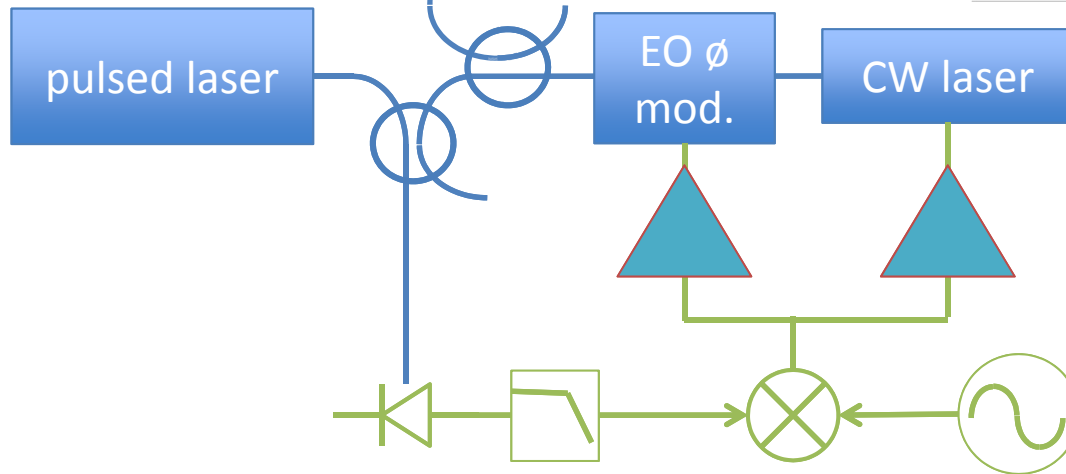
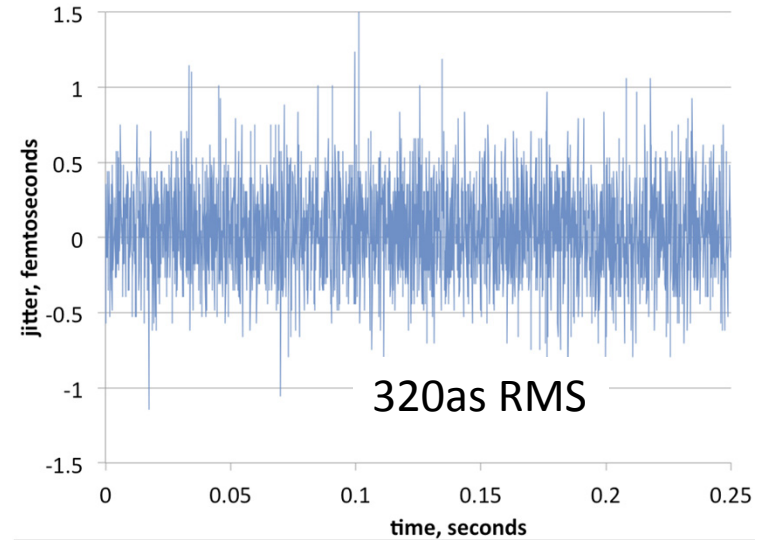
Lock CW to clock

- Optical phase-locked loop
 - Beat CW with nearest comb line
- 8kHz bandwidth piezo tuner
 - 1.8fs RMS jitter



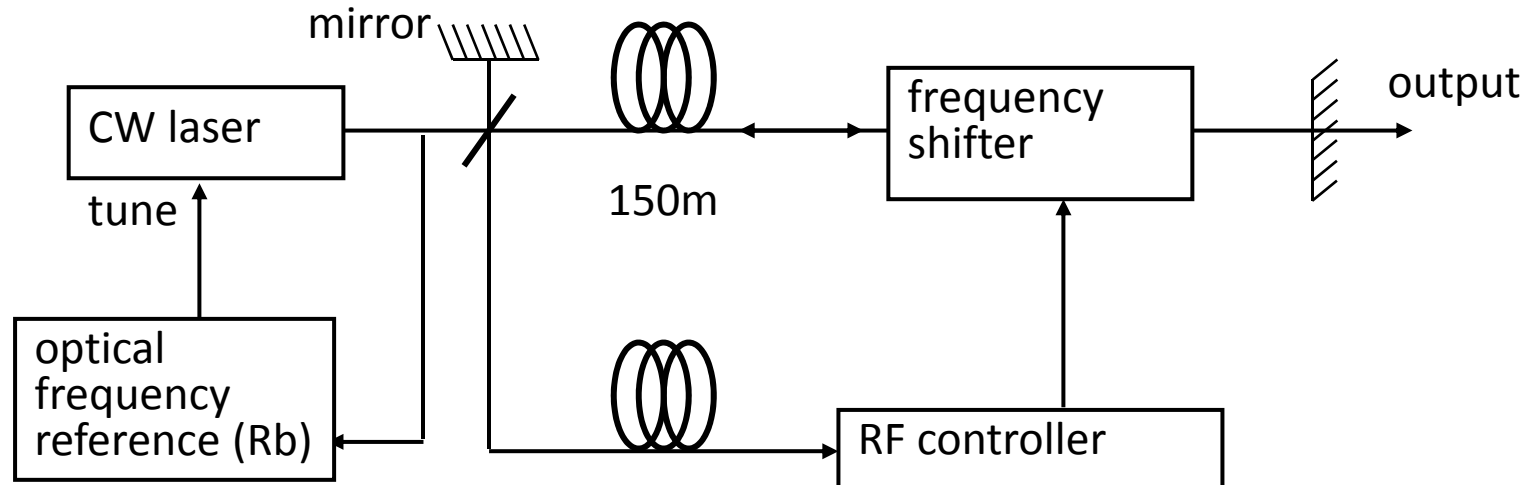
Lock CW to clock

- Optical phase-locked loop
 - Beat CW with nearest comb line
- 8kHz bandwidth piezo tuner
 - 1.8fs RMS jitter
- >1MHz EO phase modulator
 - 320as RMS jitter

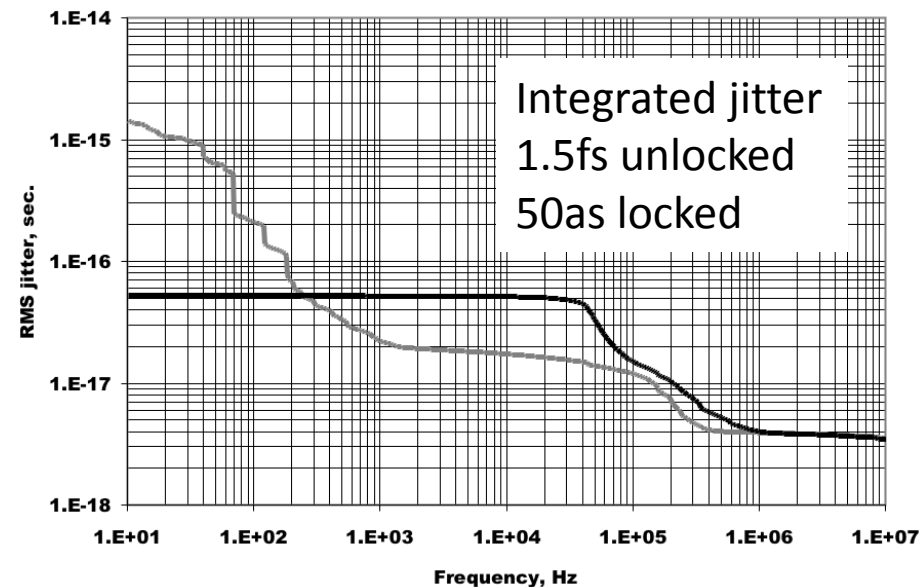


- *Fast extracavity control becomes possible when jitter is <10fs*

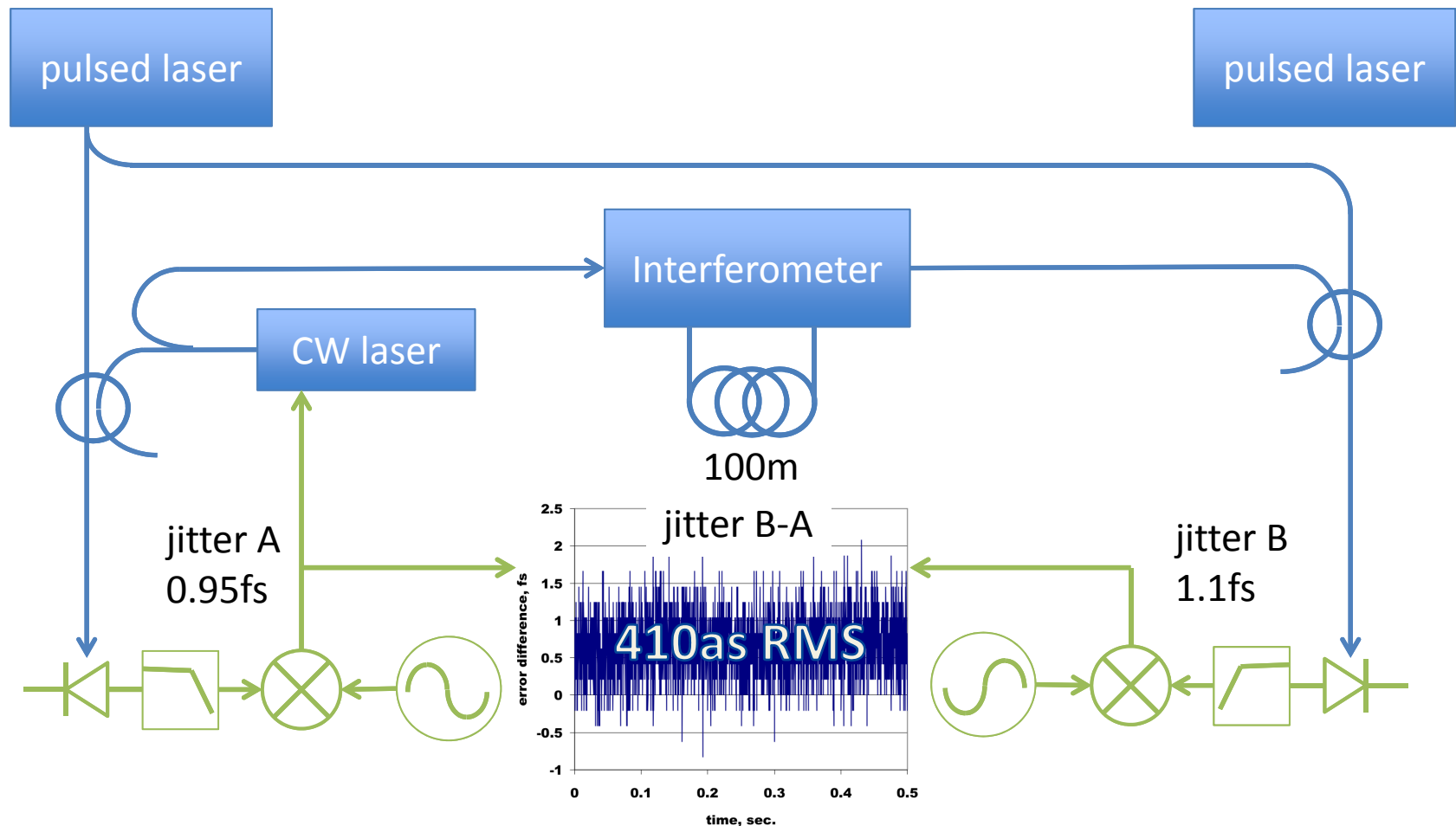
Interferometric link stabilizer



- No moving parts
- Similar device demonstrated over 500km fiber (Science 336, 441 (2012))
- Tracks phase continuously
 - Nanosecond error range
 - Sub-fs precision



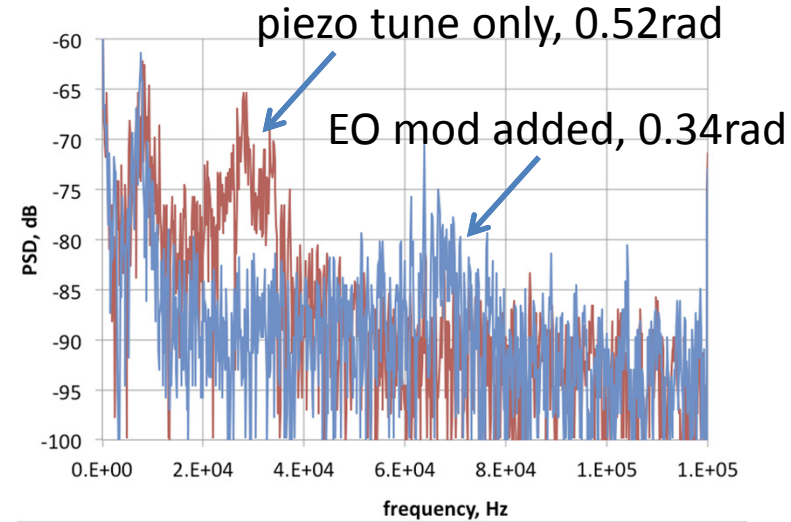
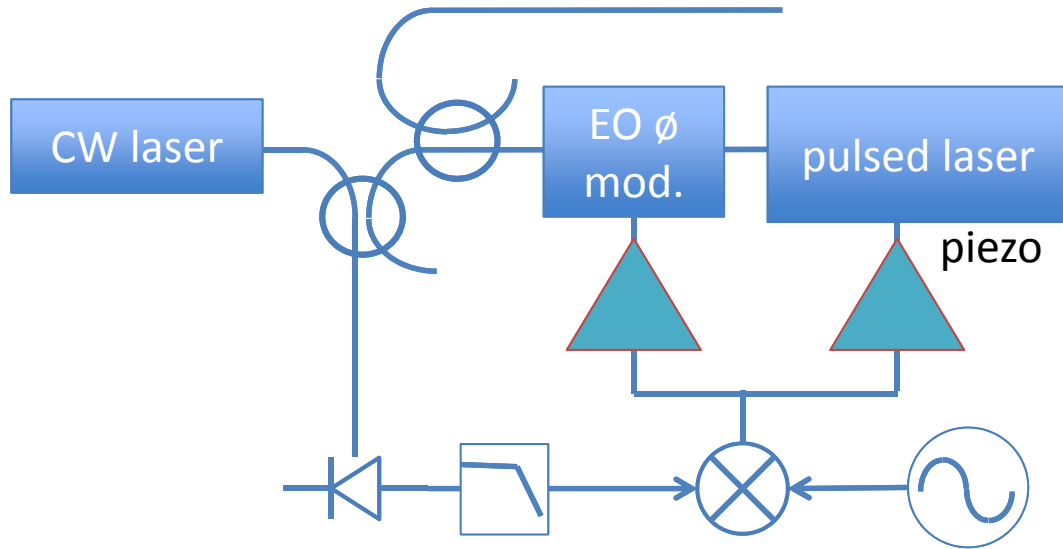
Link transmission jitter



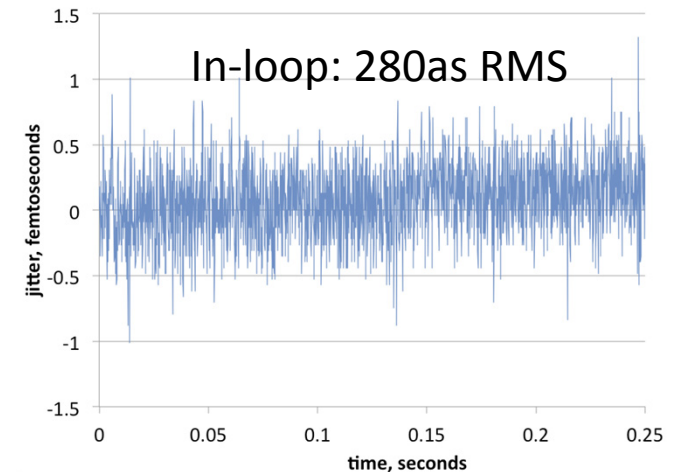
- Transmission over 100m fiber adds ~400as to optical jitter

Control of laser timing

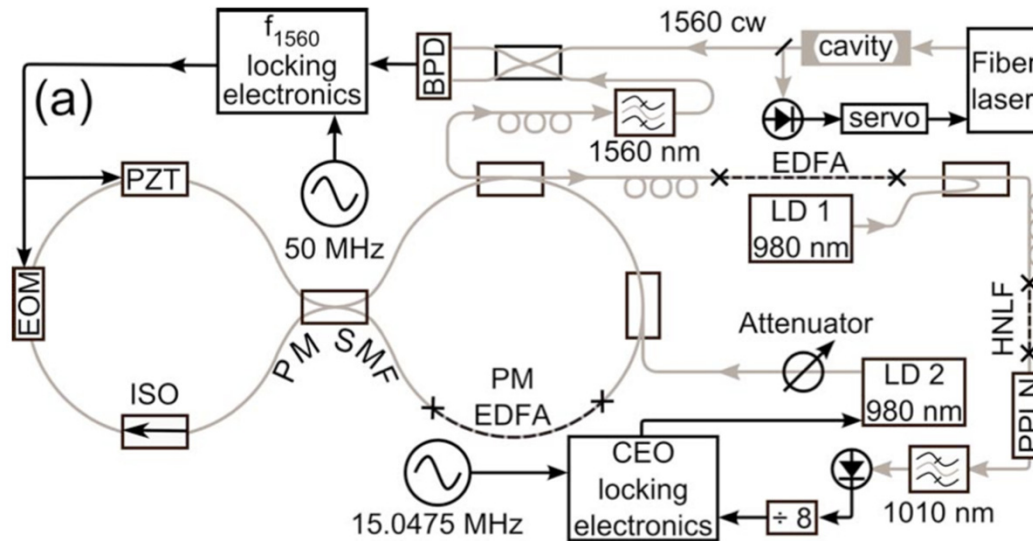
Lock pulsed laser to CW



- Control rephase based on CW laser phase
- Increase control BW with EO
- Pulsed laser not CEP stable



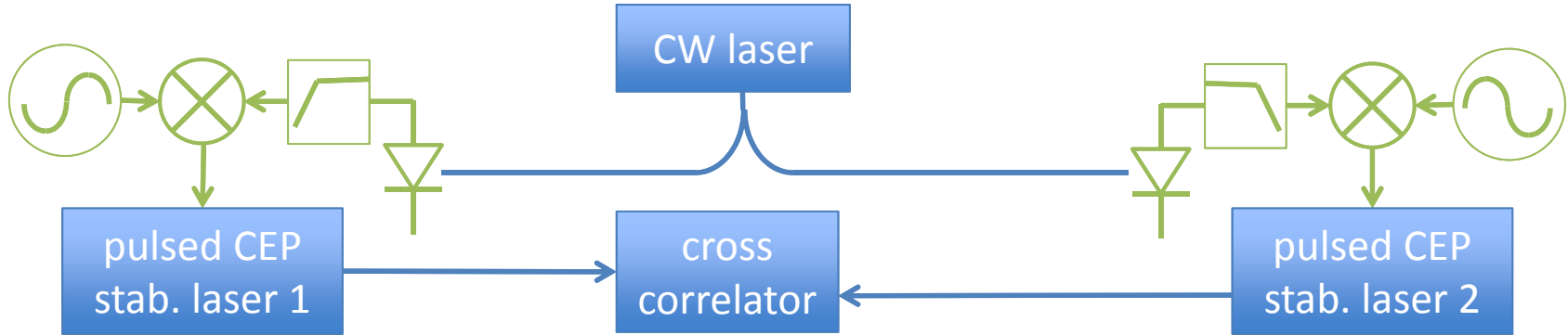
CEP-stabilized fiber laser locked to CW



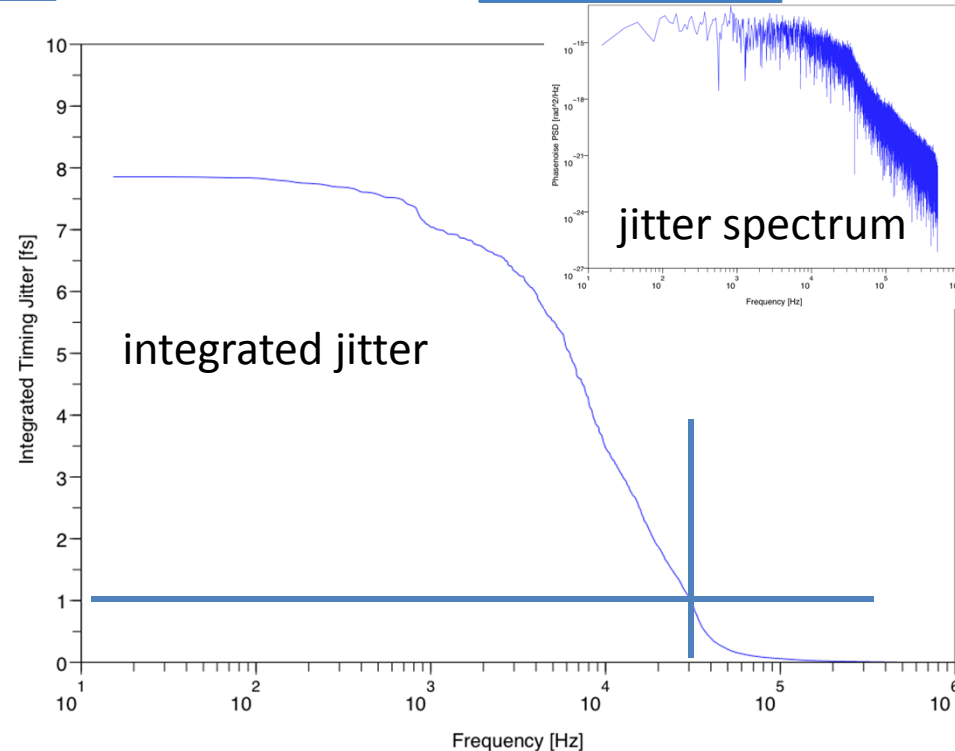
Baumann et al
Opt. Lett. 34, 638 (2009)

- 0.138 radian envelope-to-CW phase (113as at 1550nm)
 - With intracavity electro-optic modulator
 - Envelope synced to CW phase with 113as RMS jitter

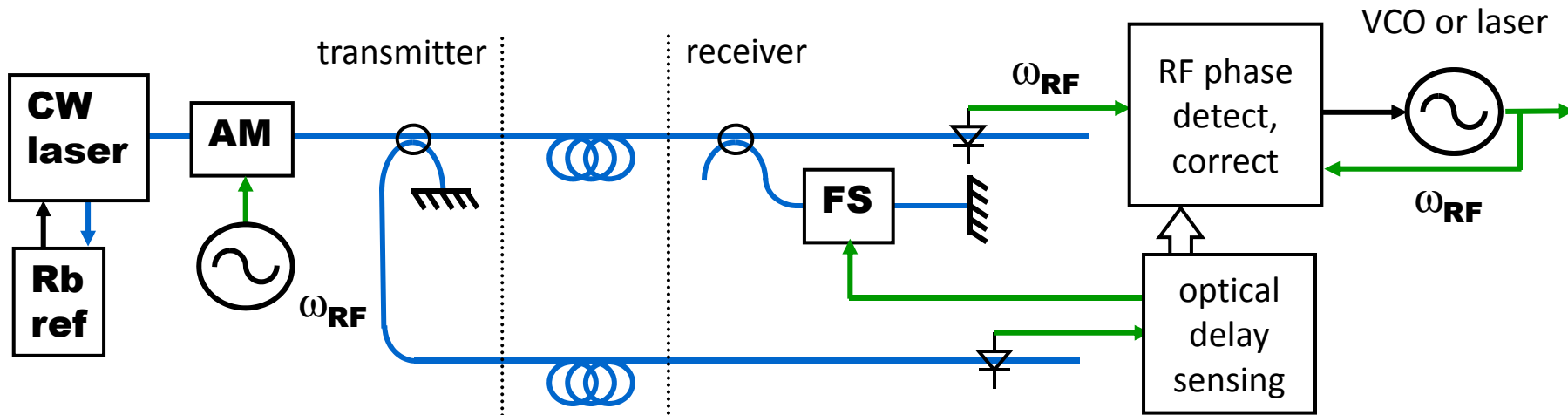
Cross-correlation of locked lasers



- <8fs RMS difference, 10Hz to 1MHz
- $8\text{fs}/\sqrt{2} = 5.6\text{fs}$
- Most noise below 100kHz
- Limited control bandwidth
 - Increase BW to 1MHz with EO crystal in cavity

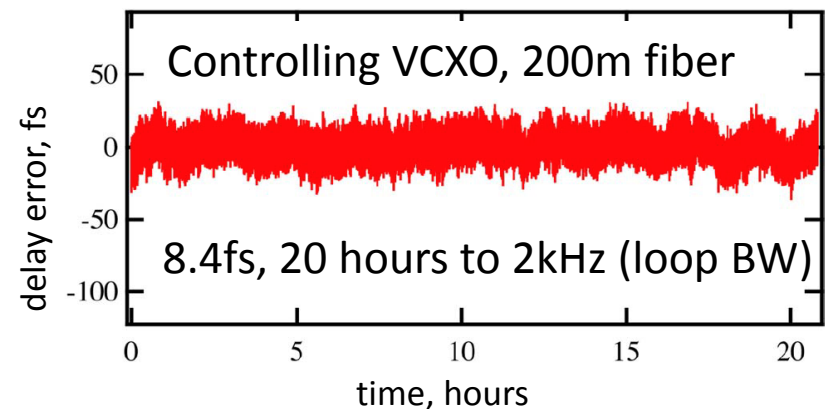


Need to first “coarse” lock at 10s of fs



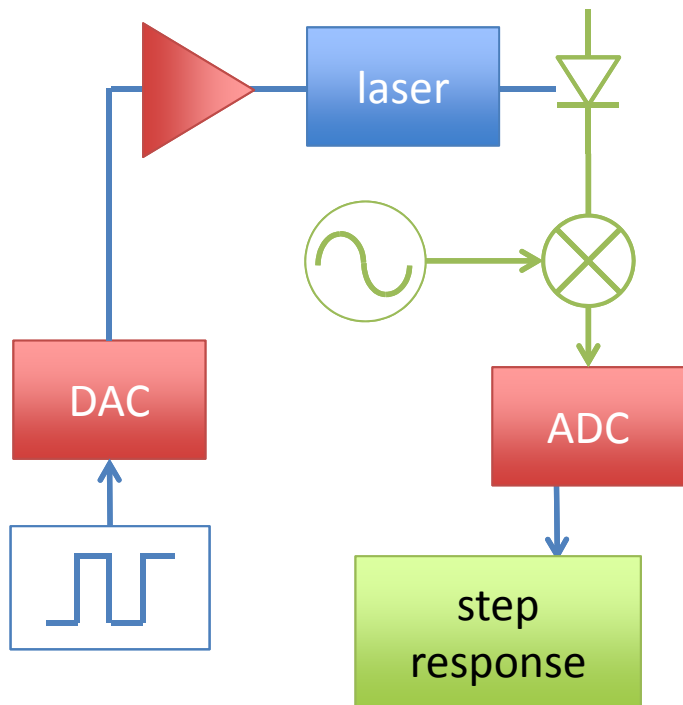
- RF clock controls remote oscillator
- ~10fs is the limit
 - 0.01 degree phase error
 - 10fs at 3GHz
- Currently used in LCLS and Fermi@Elettra

Out-of-loop results:

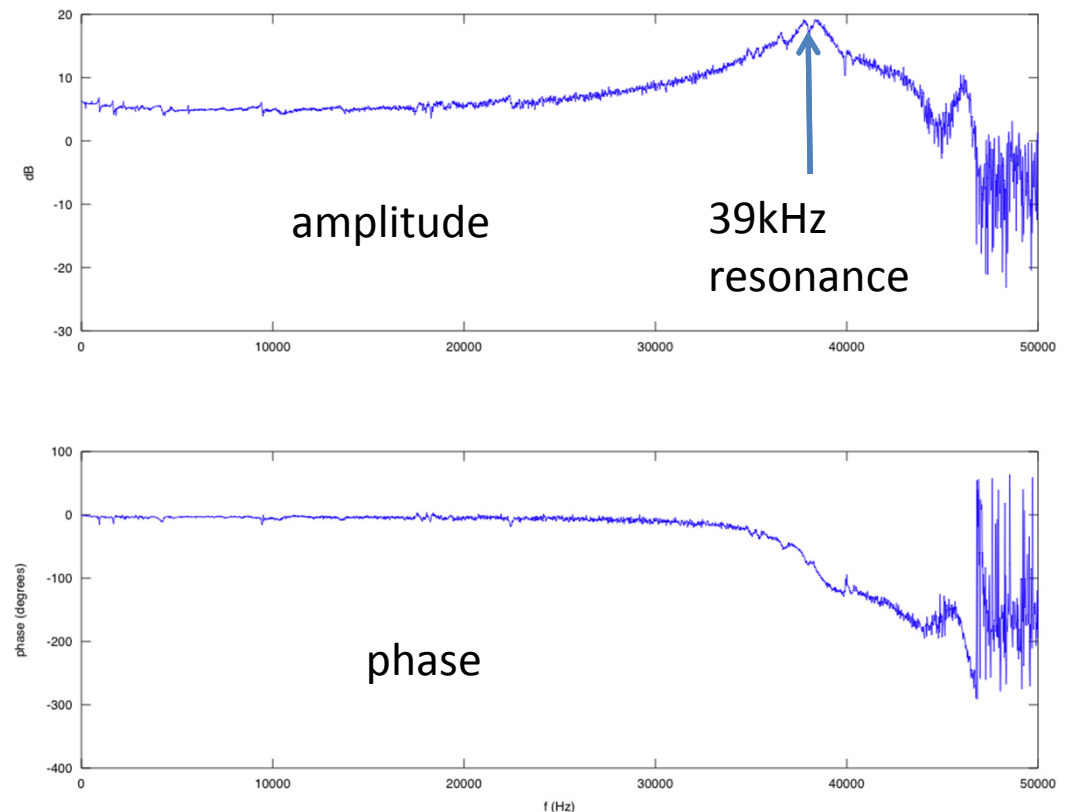


Optimizing RF lock for ti:sapphire laser

- Determine open loop transfer function
- Add filter to prevent oscillation with high gain (30kHz LPF)



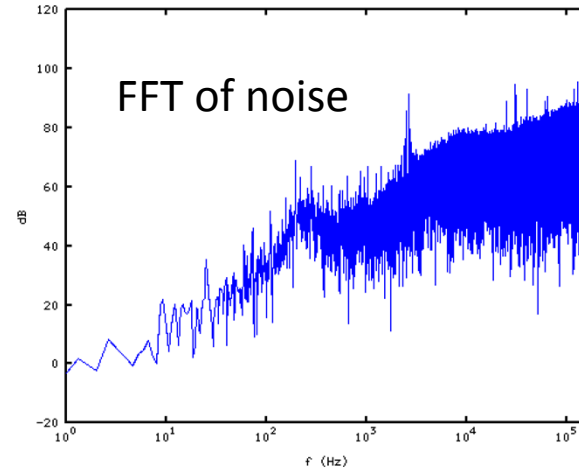
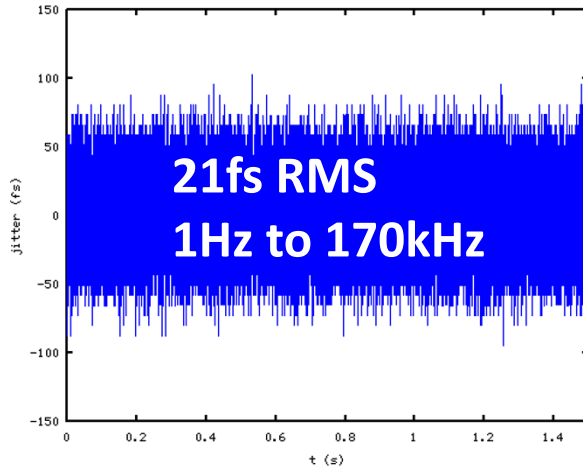
Transfer function:



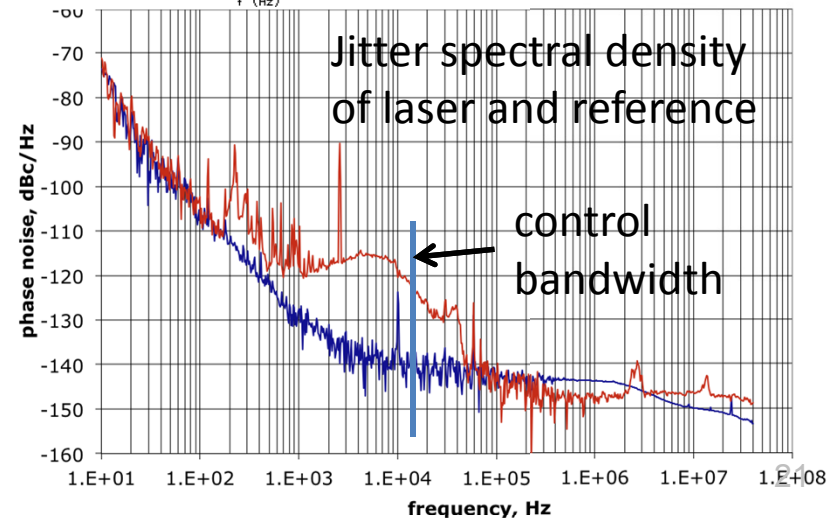
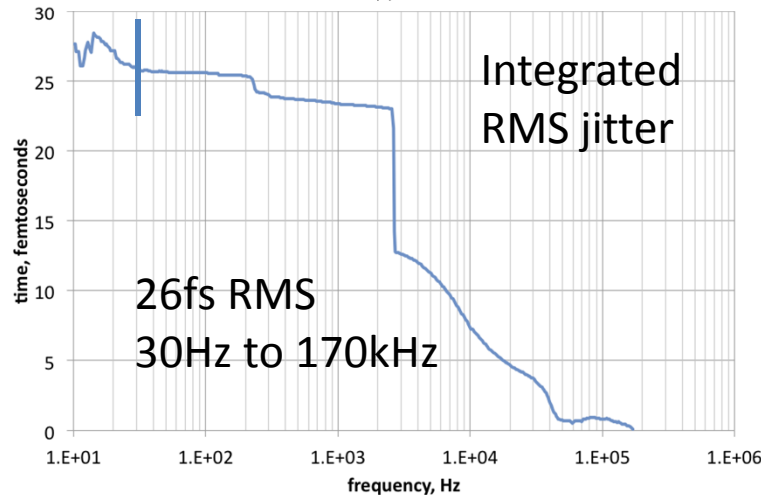
RF locking results with tisaf

- In-loop measurement compared with difference between two externally referenced measurements

In-loop:



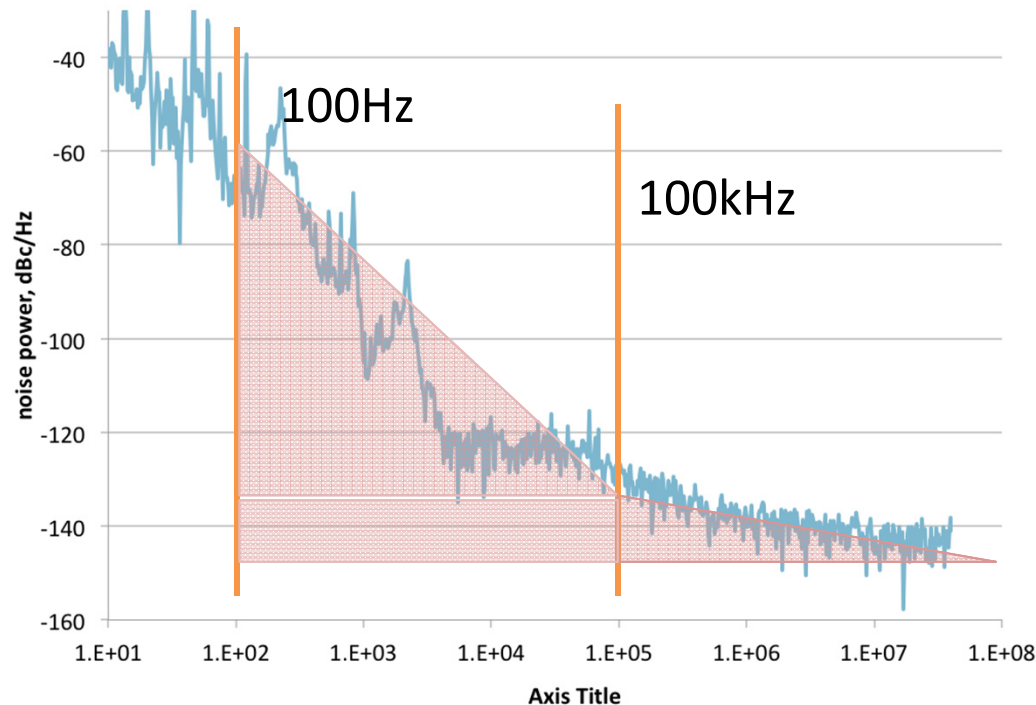
Out-of-loop:



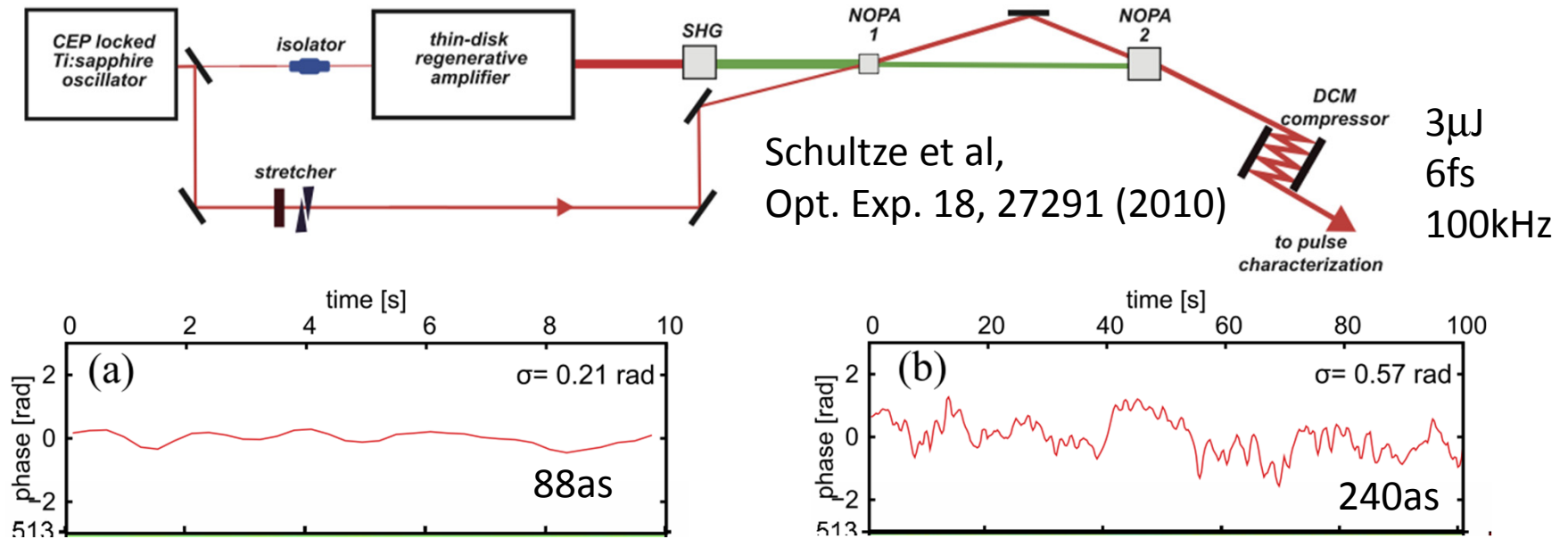
Downstream monitors and feedback

Noise measurement and control depends on repetition (sample) rate

- High reptime enables high bandwidth feedback
 - Control BW $\approx$ sample rate/10
- Integrated jitter above sample rate is “shot to shot”



Effect of amplifiers on CEP

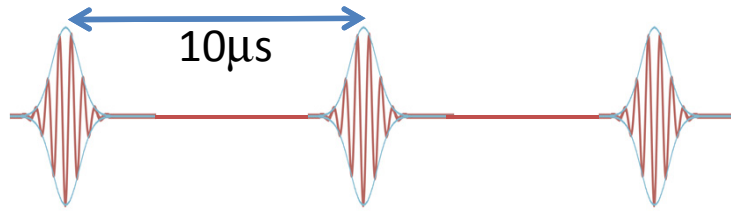


- CEP thru example optical parametric amp, 240as long term
 - Measured with a nonlinear interferometer after the amp
 - Variations due to air turbulence in compressor?

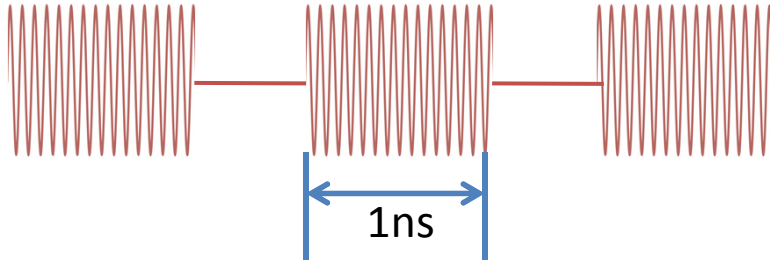
Optical pulse timing detector

time:

100kHz
pulse train



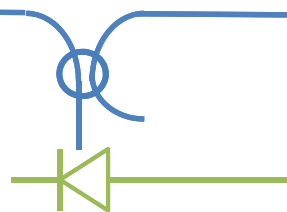
chopped
CW



CW from link



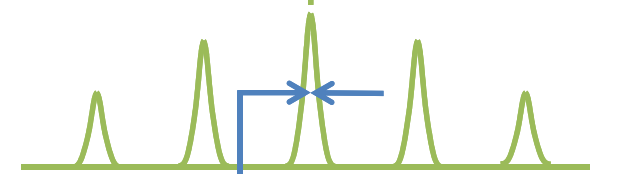
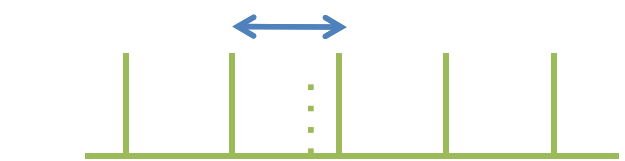
pulse train
to be timed



heterodyne beat

optical frequency:

100kHz

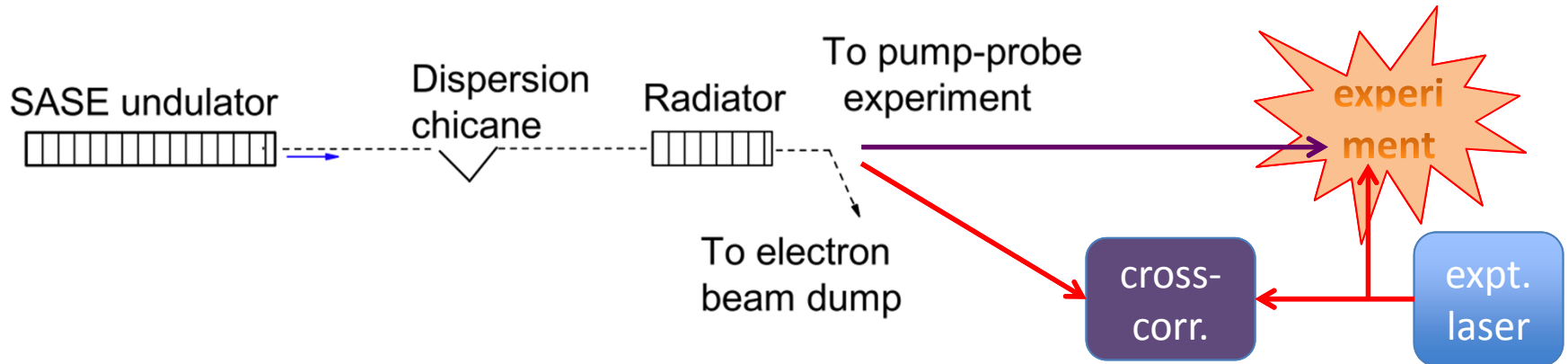


1GHz (10^4 lines)

<1kHz
linewidth

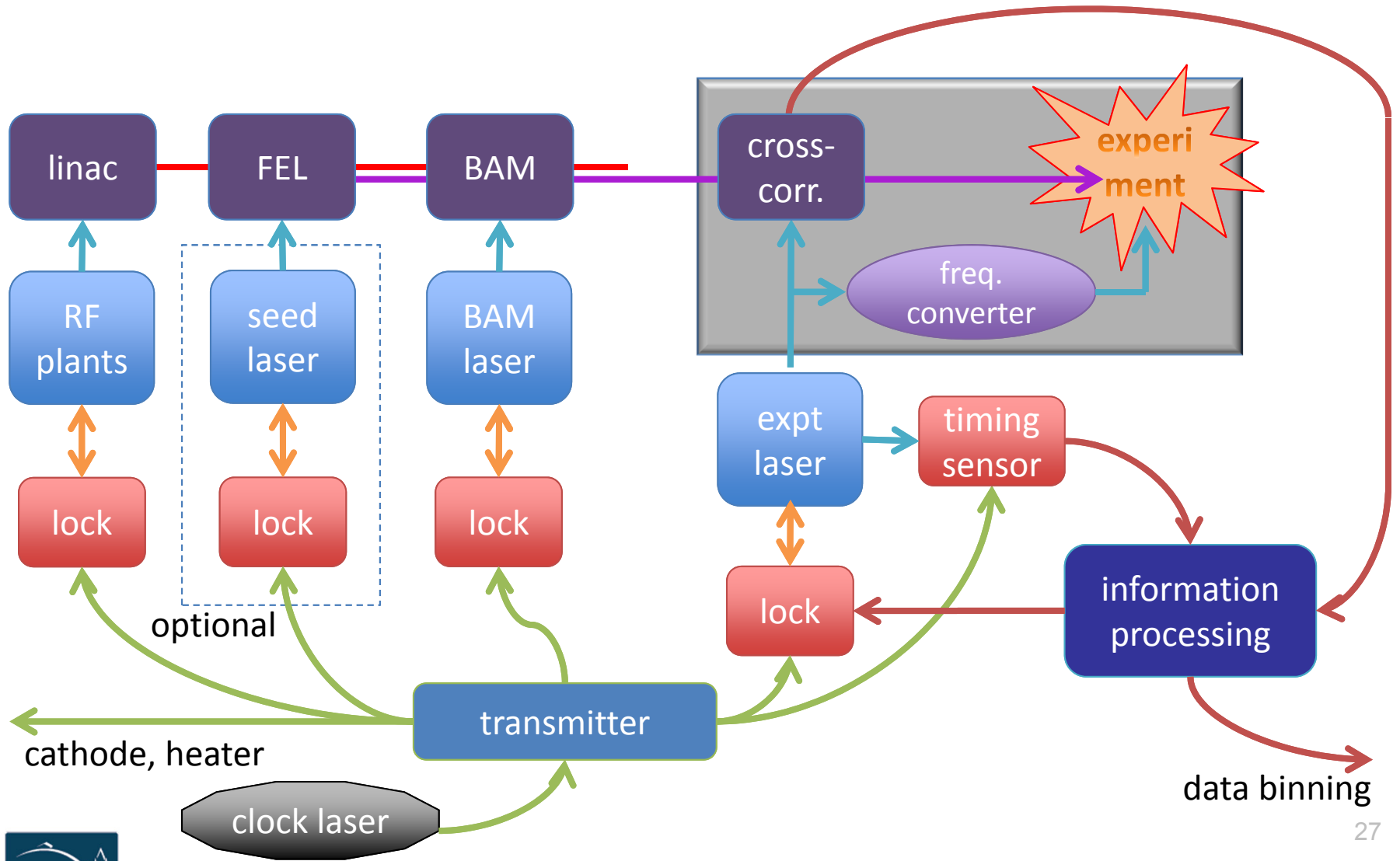
- Same heterodyne scheme at low repute
- Beat frequency is down at ~20kHz
 - More noise, narrow bandwidth

Cross correlating with optical radiation



- 2-color or “optical afterburner” concept
 - Saldin et al, PRST AB 13, 030701 (2010)
 - Optical synced with X-ray to 30as (10^{-4} energy jitter)
 - Cross correlate with experiment laser, sub-fs uncertainty
- X-ray/optical cross-correlators 5-10fs currently
- Use to correct long term drift
 - No need for passive thermal stability in other subsystems

Timing system block diagram



Conclusion: robust $<10\text{fs}$ sync is likely

- All subsystems capable of $\leq 1\text{fs}$ short term jitter
 - Optical phase lock provides fine timing sensitivity
 - Well developed technology for optical metrology
- Slow drift corrected based on cross-correlation at experiment
- Experiments to further demonstrate capabilities are ongoing