



movement (approx. 4370 mm.) of the sliding short. A PC-based stepper motor controlled system has been developed for the said movement.

*Dee:* The spiral shaped Dee, splitted into two halves (upper and lower dees) and symmetrical about the median plane, is located at the valley of the sc magnet. They are galvanically connected to produce symmetrical electric field. Dee-to-dee coupling is eliminated by shielding to make each dee acting as a separate capacitance w.r.t. liner (ground).

*Insulator:* A high voltage pure (99.5%) alumina insulator (loss factor  $\leq 4 \times 10^{-4}$ , Dielectric constant  $\geq 9.6$ , tensile strength  $\geq 3.5 \text{ N/mm}^2$ ) forms boundary for the vacuum envelop and allow the sliding short to operate in air. The dimension of the insulator is 285.75 mm. OD x 266.7 mm. ID x 228.6 mm. L and its end surfaces are metallized with molybdenum-manganese brazing alloy to nominal  $25\mu\text{m}$  thickness with  $5\mu\text{m}$  nickel final coat.

*Coupler:* The drive power from final power amplifier is fed to the cavity by a hydraulically driven vacuum variable coupling capacitor ( $C_c$ ) through 3-1/8 inch rigid coaxial transmission line with  $50\Omega$  characteristic impedance. The coaxial type  $C_c$  is varied from 2 to 8 pF (approx.) to match the impedance of the transmission line to the shunt impedance of the cavity.

*Trimmer:* The fine frequency tuning ( $\pm 0.3\%$ ) of the cavity is accomplished by a hydraulically driven trimmer capacitor formed between the plate inserted from top and upper half of the dee. The criterion for fine tuning the cavity is that the phase difference across the  $C_c$  is  $90^\circ$ .

## POWER AMPLIFIER

Three high power final rf amplifiers have been developed and installed at the vault. Each rf amplifier (Cross-sectional view as shown in Fig. 3) is based on Eimac 4CW 150,000E water-cooled tetrode and has max. 100 kW output at  $50\Omega$  impedance. The output tank circuit of the amplifier consists of a  $\lambda/4$  type variable length coaxial cavity. Like main Dee cavity, the short-circuited coaxial cavity is also tuned by the precise movement (with a resolution of  $50 \mu\text{m}$ ) of the sliding short (see Fig. 4 & 5) within the operating frequency range of 9 to 27 MHz under unloaded condition. The shape of the amplifier cavity is similar to that of the main cyclotron cavity, except only the length, which is 2184 mm. for amplifier.

An inductive coupling loop is inserted along one side of the cavity (through the sliding short) at  $1/5^{\text{th}}$  voltage point to reflect nearly constant impedance at the anode of the tetrode. But as the length of the loop is comparable to operating wavelength, this assumption is not valid. So, by loop area trade-off it is kept in the required range. Anode shell heavily loads the tank circuit, thus reducing the cavity length and shifting the cavity higher order modes beyond 66 MHz. The output rf power (up to  $100\text{kW}_{\text{max}}$ ) is taken out at  $50\Omega$  impedance through this inductive loop, which is matching the high cavity impedance to  $50\Omega$ .

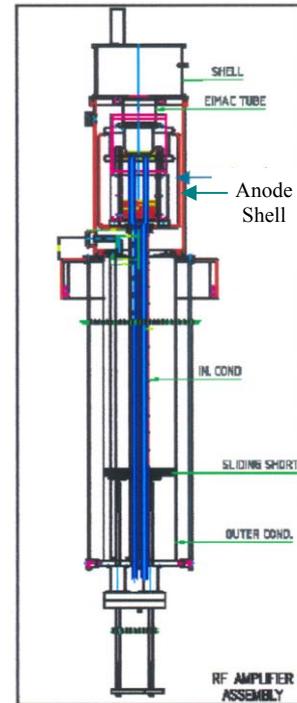


Figure 3: Cross-sectional view of high power rf amplifier

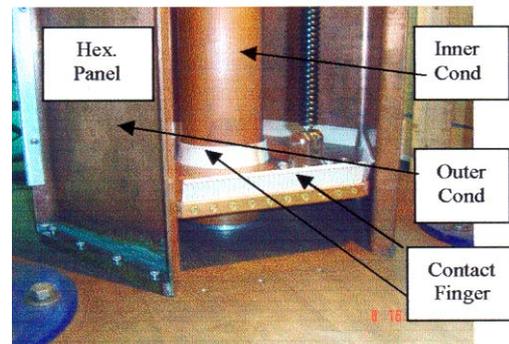


Figure 4: Sliding short contact fingers for amplifier

The four identical Bridge-T networks (see Fig. 6) in the grid of the final amplifier (shell) are driven with equal power levels of up to 150 watts each. VSWR of the input circuit of the amplifier has been measured using VNA (See Fig. 7) and obtained max of 1.14 at 18.18 MHz.

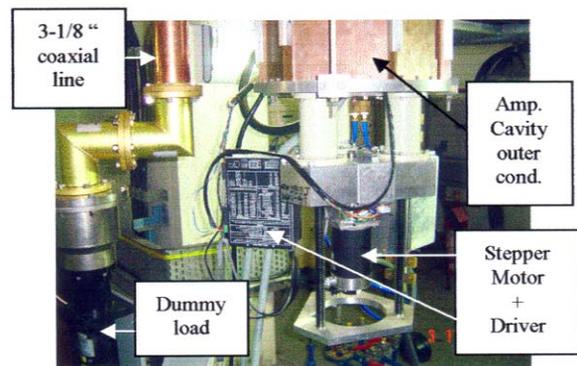


Figure 5: Stepper motor assembly with amplifier sliding short



Figure 6: Input circuit (assembled) for amplifier

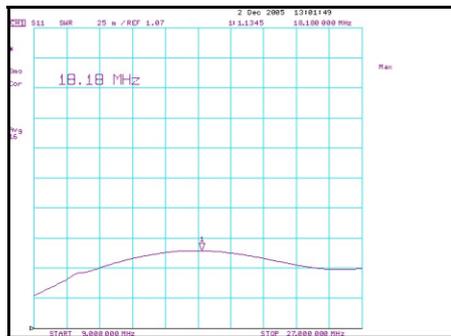


Figure 7: VNA measurement of input VSWR

The anode of the tetrode is coupled to the cavity by a cylindrical Blocking capacitor as shown in Fig. 7.

The measured unloaded  $Q$  of the cavity varies from 4300 to 1800 and the measured loaded shunt impedance values vary from  $5\text{k}\Omega$  to  $1\text{k}\Omega$  within 9 MHz to 27 MHz.

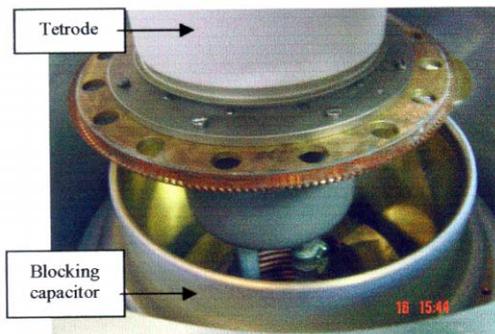


Figure 8: Tetrode assembly with blocking capacitor

### LOW-LEVEL RF

RF signals from  $3$ -phase generator unit, pass through *Manual phase shifter unit* to get adjusted of the relative phase between three signals, if any phase asymmetry occurs. Then the signal passes through two closed loop Systems – *Dee voltage regulator unit (DVR)* for amplitude regulation and *Phase regulator unit* for phase regulation. As Phase loop produces some residual amplitude modulation, amplitude loop precedes the phase loop. After *phase regulator unit* the signal is directly amplified to 600W level by *solid-state driver amplifiers* (2 nos. of ENI#A300) and then to 100kW level by Eimac

tetrode based tuned *final rf power amplifier* for feeding to the main Dee cavity of the cyclotron.

In  $3\phi$ -generator, phase shifting of  $120^\circ$  is done by double mixing and auxiliary transmission line based technique, thereby making insensitive to frequency change. Phase imbalance between 3 channels is  $<\pm 1^\circ$  and amplitude unbalance is  $<\pm 0.2$  dB with harmonic content less than  $-40\text{dBc}$ . The *manual phase shifter* is based on classical I&Q modulator [3] using M/ACOM QH-6-4 quad hybrid, MCL-ZAS-3 electronic attenuator and MCL-ZFSC-2-1 splitter. In normal operation  $\pm 15^\circ$  variation is sufficient and output signal balance is  $<<\pm 0.05$  dB with harmonic content  $< -38\text{dBc}$ .

*DVR* is based on AD834JN RF Modulator [4] that modulates the RF drive signal according to the error signal between highly stable dc reference (REF01) and the feedback sample obtained from Dee pick-up signal.

Any deviation from sample phase from the reference phase is detected by the *phase detector* that produces dc error signal, which, in turn, controls online I&Q phase modulator and lock the phase to its reference within working limit of  $\pm 60^\circ$  and error bandwidth of 1 kHz. *Phase detectors*, based on double balanced mixer, have been fabricated using MCL-RPD-1 having response of  $8\text{mV/degree}$  in  $+8\text{dBm}$  saturated mode. The phase detectors are used as window comparator to generate trigger signal if the phase of rf signal, due to fast phase change, crosses the predetermined value, and thereby indicating the occurrence of Sparking.

### ACKNOWLEDGEMENT

The authors would like to thank all staff of VECC and especially to RF (Electrical & Mechanical) staff for their active participation and help to carry out this job.

### CONCLUSION

Three nos. of high power final rf amplifiers including PC-based stepper motor controlled drive system for sliding shorts have been developed and installed at vault. LLRF control electronics have been developed and tested successfully. Assembly of main dee cavities are in progress and warm rf test of these cavities is expected to be carried out soon.

### REFERENCES

- [1] S. Som and P.K. Khemka, "RF cavity analysis using PC-SUPERFISH Code", IEEE Conf. (MIA-ME, 1997), p.179.
- [2] K. Halbach and R.F. Holsinger, "SUPERFISH--A computer program for evaluation of rf cavities with cylindrical symmetry", Particle Accelerators, Vol.7, 1976, pp. 213-222.
- [3] A. Bossotti, et. al, "Accelerating voltage amplitude and phase stabilization for Milan Superconducting Cyclotron", EPAC-1998, Rome.
- [4] K.L. Erdman, et.al, "Some aspects of control and stabilization of RF accelerating voltage in TRIUMF Cyclotron", AIP Conf. on Cyclotron, 1972.