

DEVELOPMENT OF RF SYSTEM FOR K500 SUPERCONDUCTING CYCLOTRON AT VECC, KOLKATA

S. Som, R.K.Bhandari,
Saikat Paul, et.al.

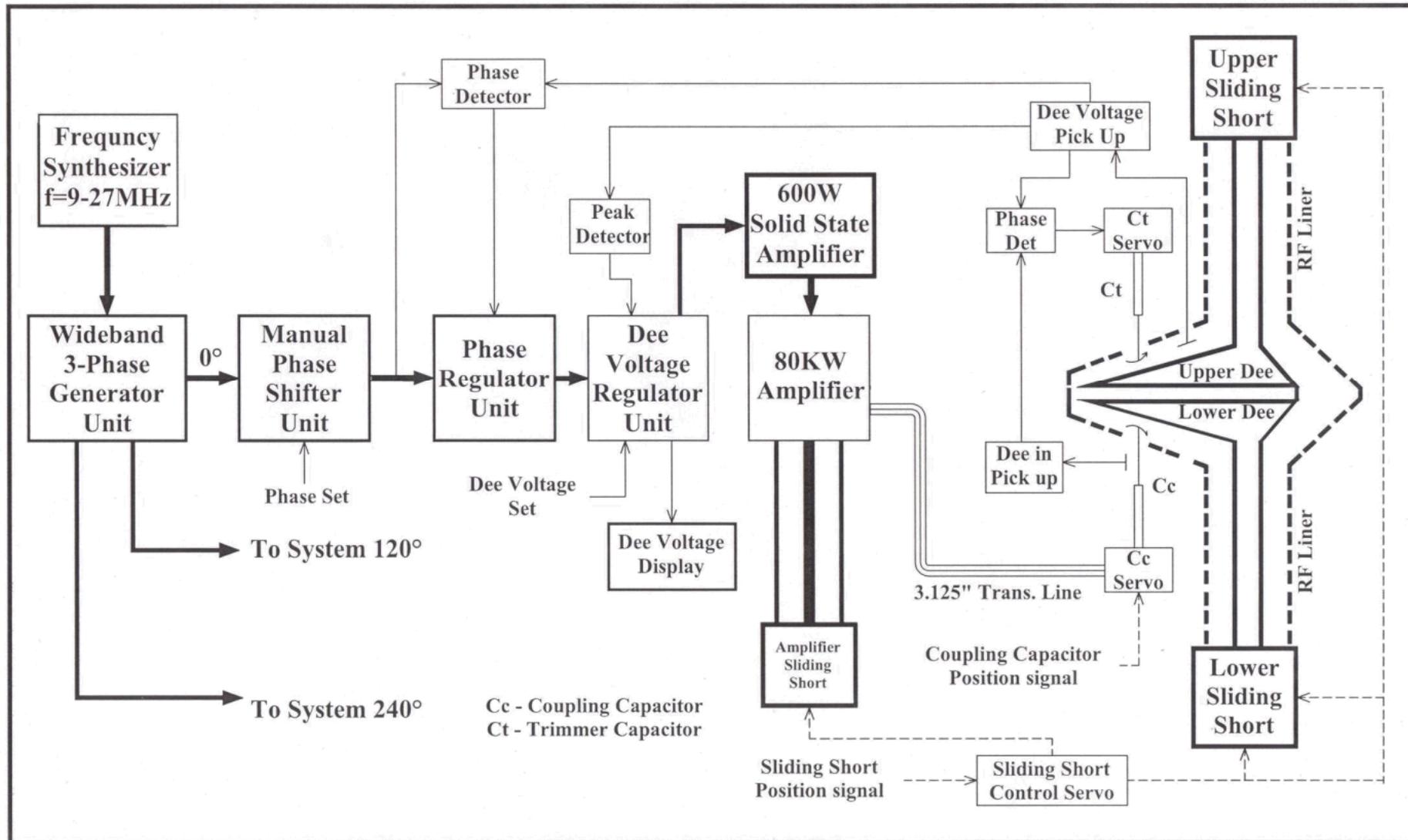


Variable Energy Cyclotron
Centre
Kolkata, India

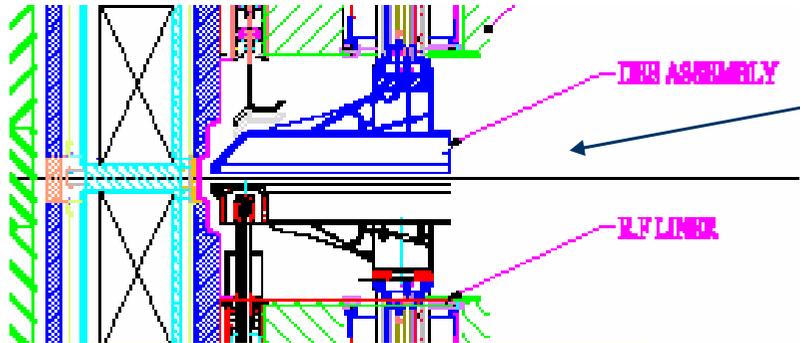
RF SYSTEM SPECIFICATION

Frequency range:	9 to 27 MHz
Harmonic Modes:	1,2,3,4,5,7
Peak Dee Voltage:	100 kV
Frequency Stability:	1×10^{-7}
Amplitude Stability:	1×10^{-4}
Phase Stability:	$\pm 0.5^\circ$

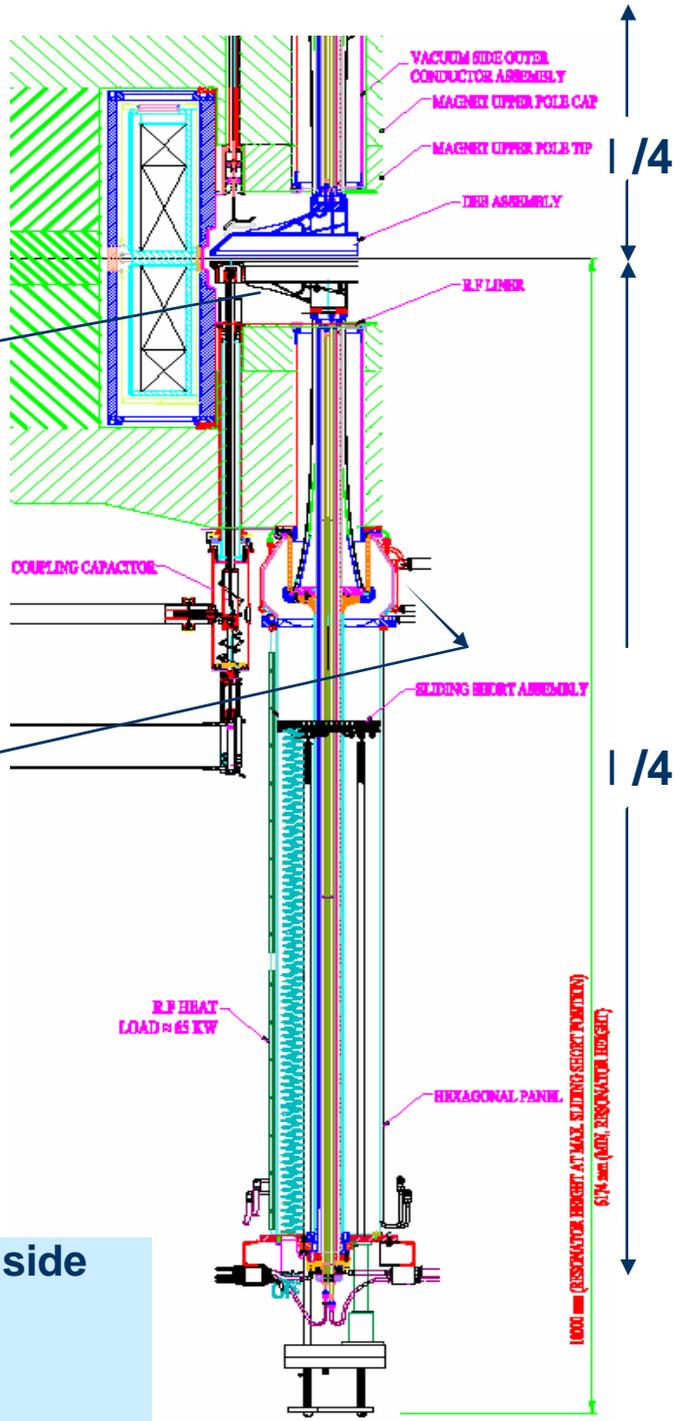
BLOCK DIAGRAM OF K-500 RF SYSTEM



MAIN DEE CAVITY WITH DEE STEM

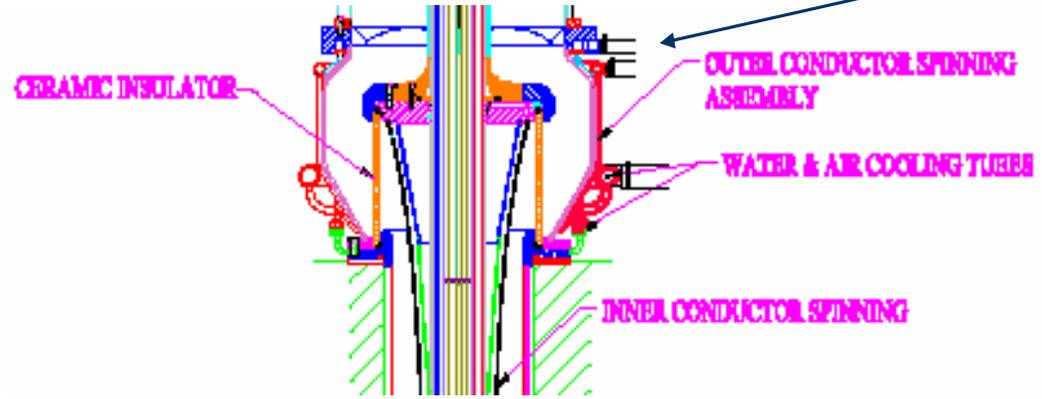


Close view



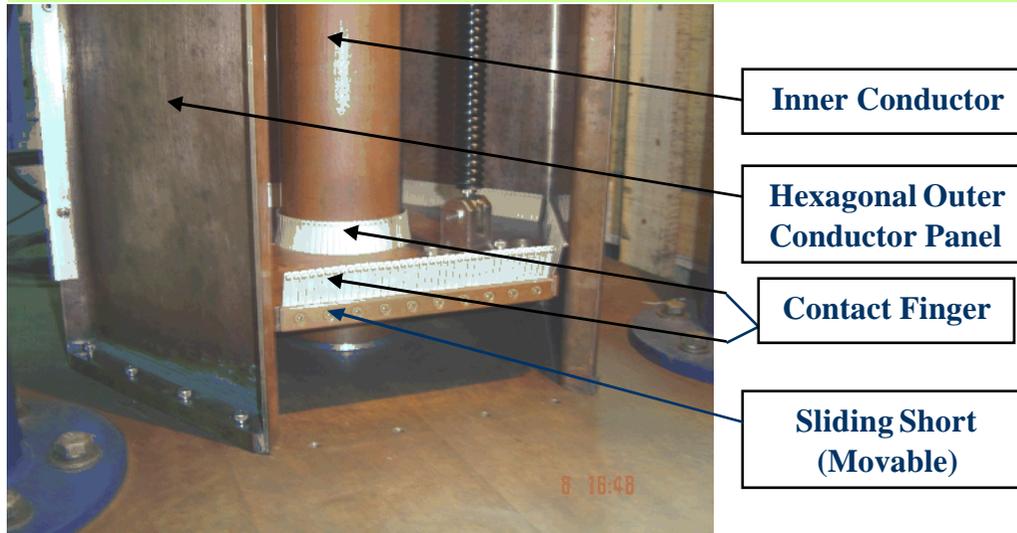
Close view

- Alumina (ceramic) insulator (99.5% purity)
- $\tan \delta = 0.0004$, Dielectric Const. ≈ 9.6
- Tensile strength $\approx 3.5 \text{ N/mm}^2$
- 285.75 mm. OD x 266.7 mm. ID x 228.6 mm. L



- Hexagonal Outer Conductor (in air): $201.65 \pm 0.05 \text{ mm}$ each side
- Cylindrical Outer Conductor (in vacuum)
- Cylindrical Inner conductor (in air): $58.42 \pm 0.05 \text{ mm. OD.}$
- Tapered Inner Conductor (in vacuum)

SLIDING SHORT ASSEMBLY FOR CAVITY



- | Sliding short plate electrically connected to inner & outer conductors of coaxial cavity by Be-Cu contact finger with silver-graphite (99%Ag +1%C) ball at the tip.
- | Contact resistance ~ 0.7 mW per finger.
- | Contact finger can carry current up to 4A/mm.
- | Each finger can withstand force ~ 0.35 kg.

- | Inner & outer conductor aligned concentric within ± 0.25 mm., because large assymetry may give rise to uneven stress on the contact finger.
- | Less contact pressure \Rightarrow higher probability of arcing.
- | Higher contact pressure \Rightarrow more load on stepper motor.
- | Coarse frequency tuning of the cavity is accomplished the precise movement of sliding short.
- | Sliding short travel ~ 4370 mm. (max.) from lowest to highest frequency.

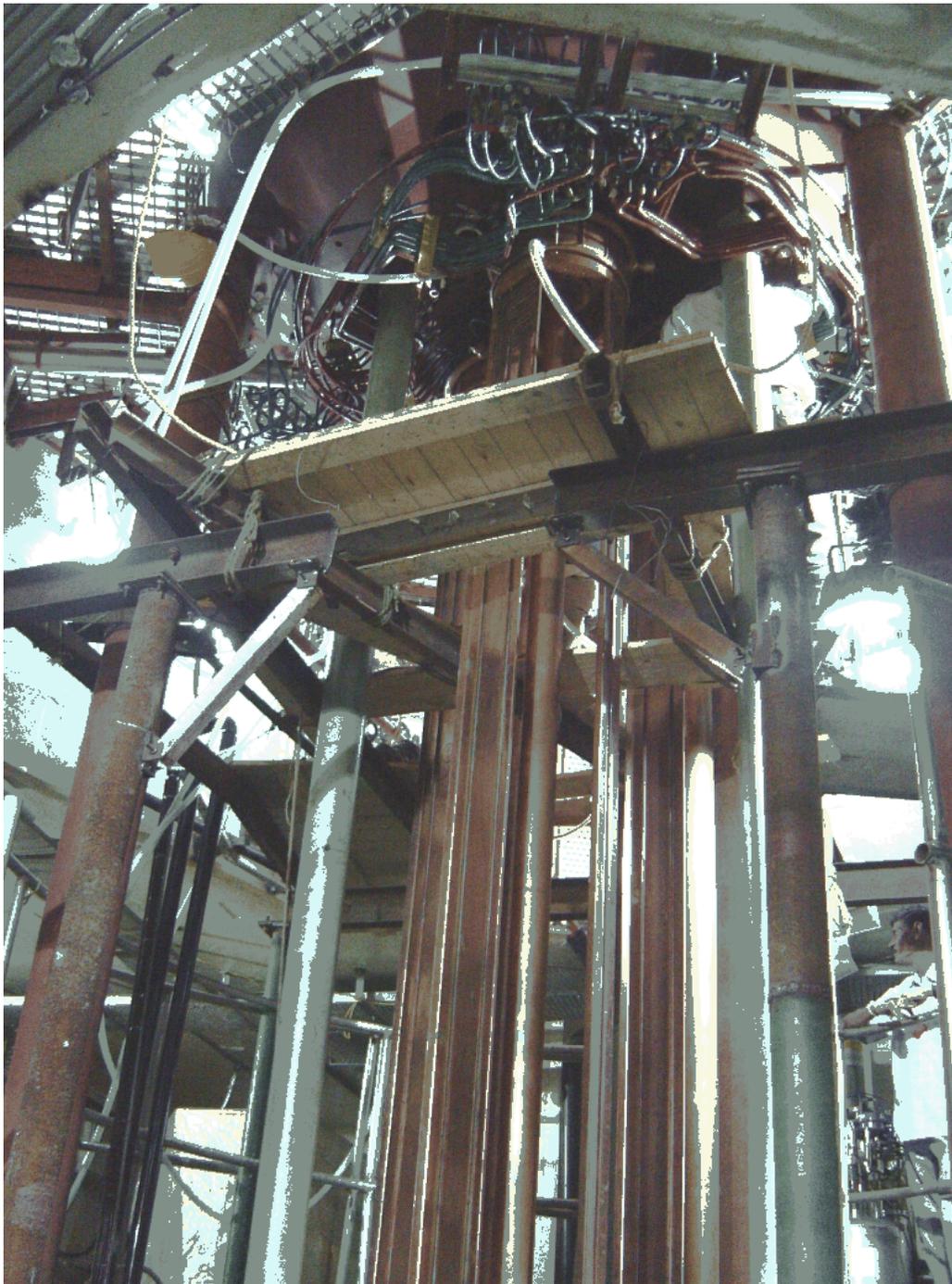
ACCELERATING ELECTRODE (DEE)

Accelerating electrode (DEE)

- | **Spiral shaped**
- | **Dee angle ~ 53°**
- | **No. of Dees : 3 lower + 3 upper**
- | **Made of OFHC copper**
- | **Kept in vacuum (~ 1 x 10⁻⁷ torr.)**
- | **Lower Dee housed with cryopanel**
- | **Water-cooled**
- | **Max. Dee Voltage ~ 100 kV**
- | **RF power coupled to lower Dee through Coupling Capacitor**
- | **Trimmer capacitor (fine Tuner) formed with upper Dee.**

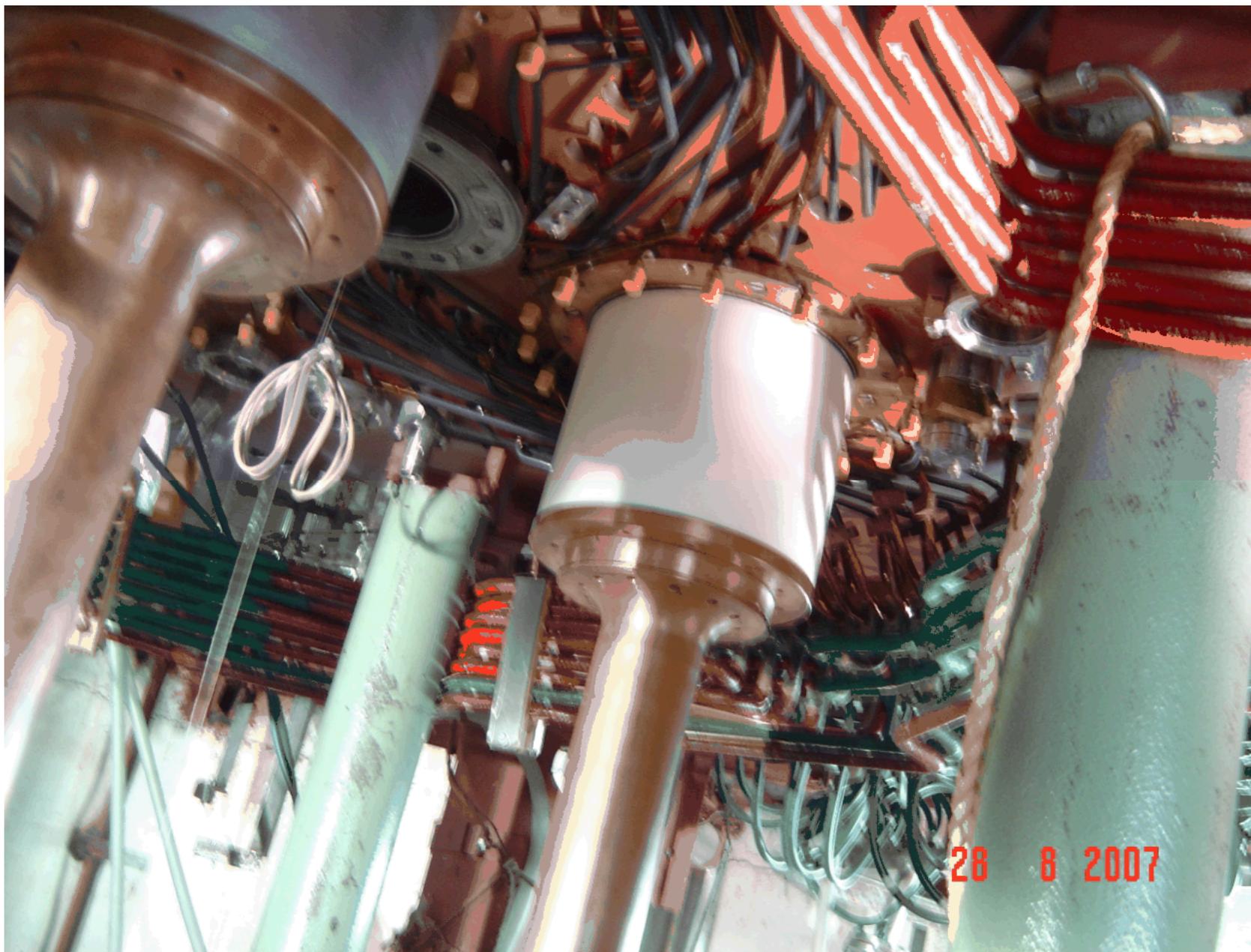


“DEE” assembly during inspection



**3 NOS. OF
LOWER RF
CAVITY
ASSEMBLY
IS IN PROGRESS**

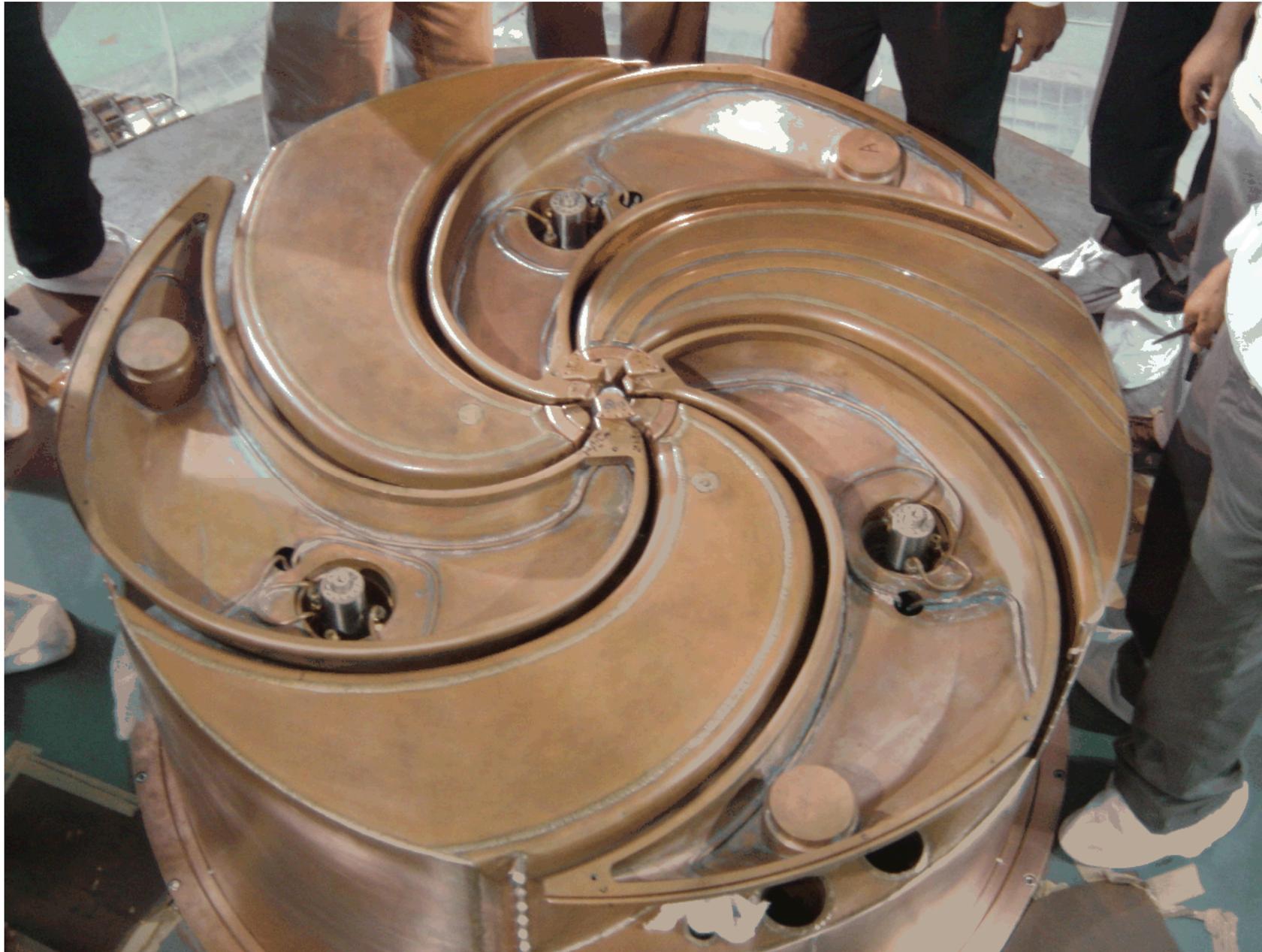
ASSEMBLY OF ALUMINA INSULATOR IN MAIN DEE CAVITY



ASSEMBLY OF INNER CONDUCTORS OF MAIN DEE CAVITIES

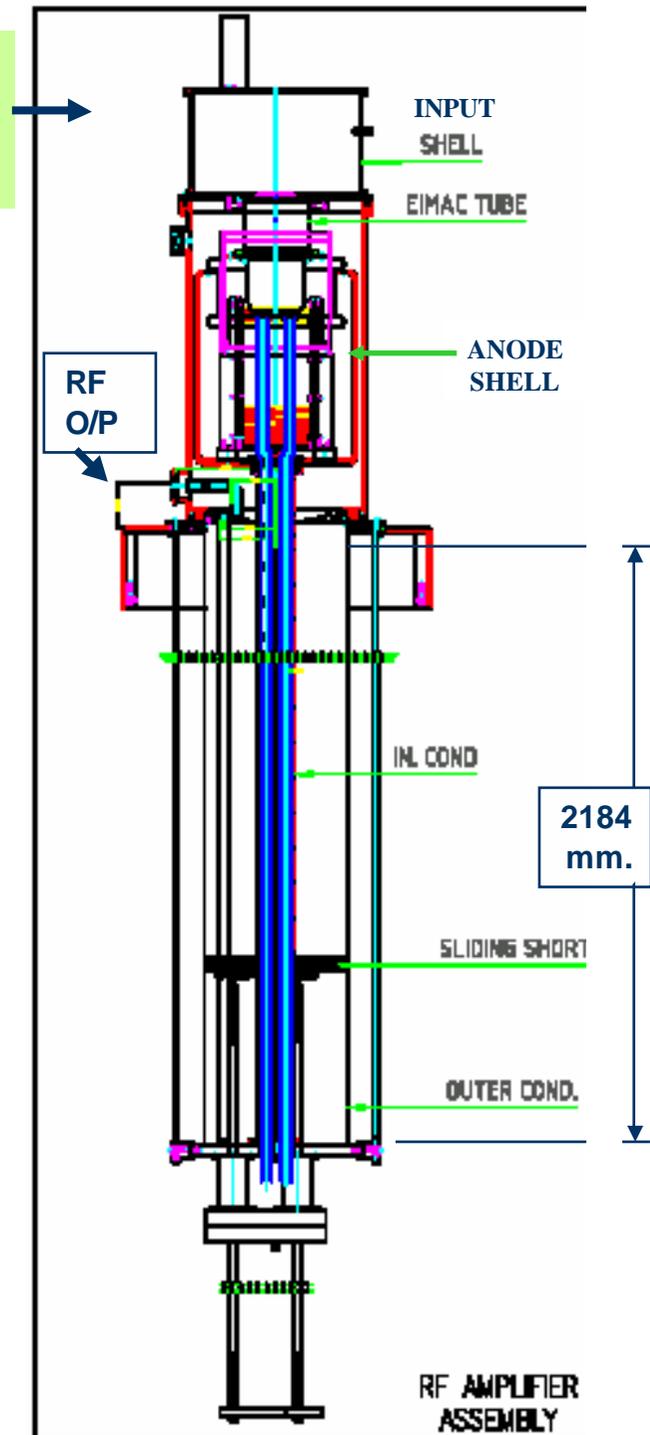


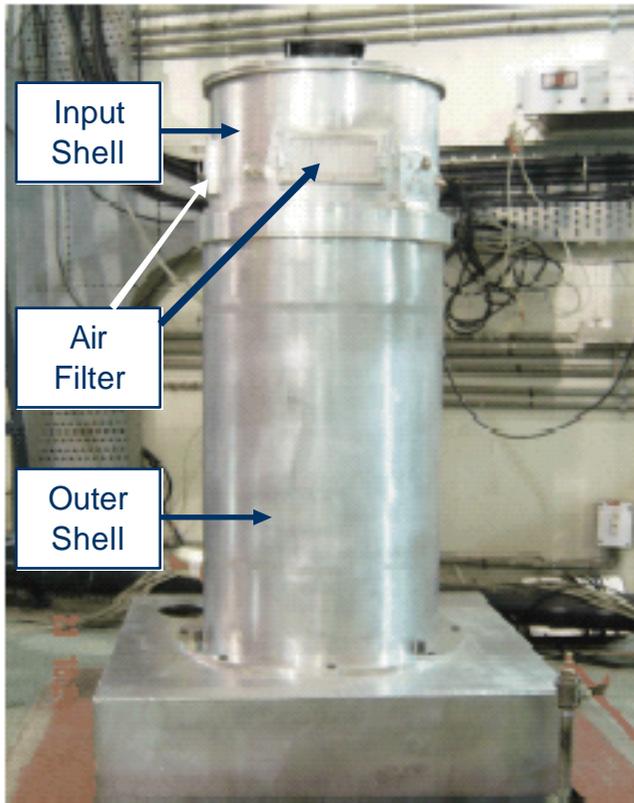
ASSEMBLY OF LOWER DEES OF SUPERCONDUCTING CYCLOTRON



CROSS-SECTIONAL VIEW OF RF POWER AMPLIFIER

- Eimac 4CW 150000E Tetrode based power amplifier
- Output Power: 100 kW max. at 50 Ohm
- Power gain ~ 22 dB
- Input Power: 600 W at 50 Ohm
- Mode of operation: Class AB
- 1/4 Resonant cavity similar to main Dee-cavity
- Tunable from 9 MHz to 27 MHz by movable Sliding short
- Sliding short travel ~ 2184 mm. max.
- Precise movement of sliding short (with resolution ~ 50 mm.)

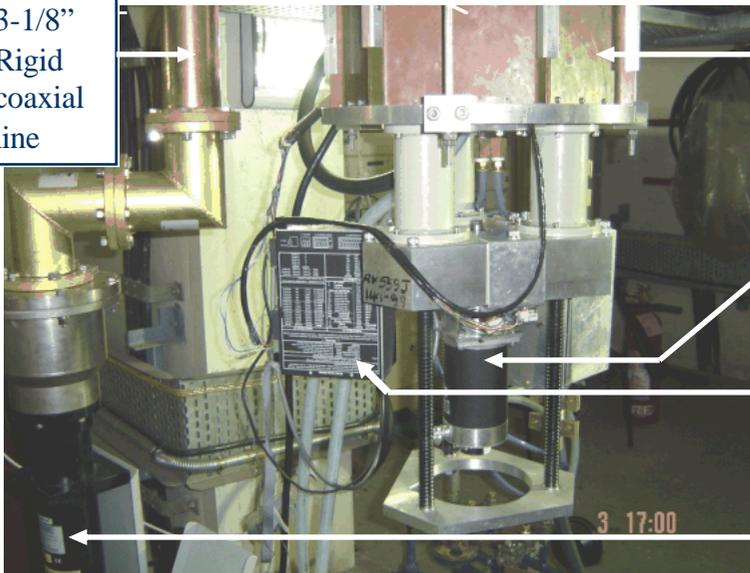




RF AMPLIFIER: PC-based Stepper motor controlled drive system for sliding shorts

- High power RF Amplifier installed at vault/basement of SCC building
- Top portion of RF Amplifier consisting of Input matching circuitry, Blocking capacitor, Screen by-pass capacitors, tetrode etc. (inside the shell) are located at vault
- Bottom portion of RF Amplifier consisting of Coaxial cavity with movable sliding short, stepper motor/Driver, Output rigid coaxial line etc. are located at the basement (below vault floor)

3-1/8"
Rigid
coaxial
line

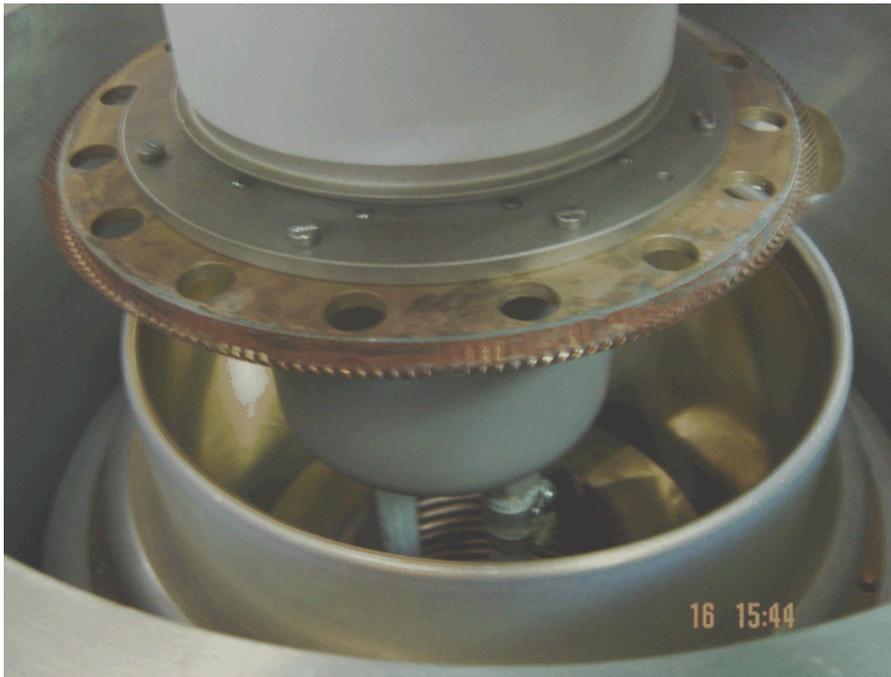


Amplifier
Cavity
outer
conductor

Stepper
Motor
+
Driver

Dummy
load

RF AMPLIFIER: ASSEMBLY OF TETRODE



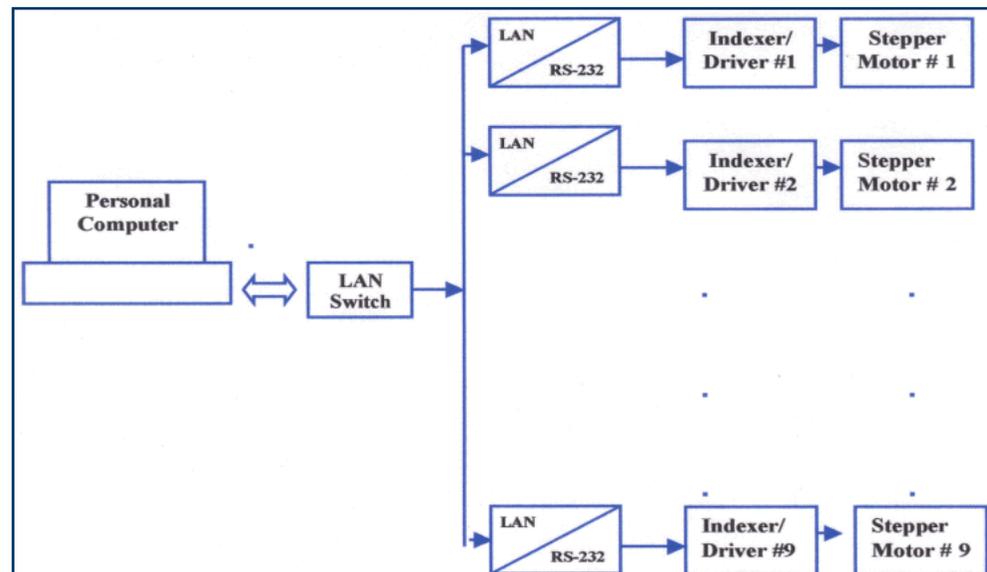
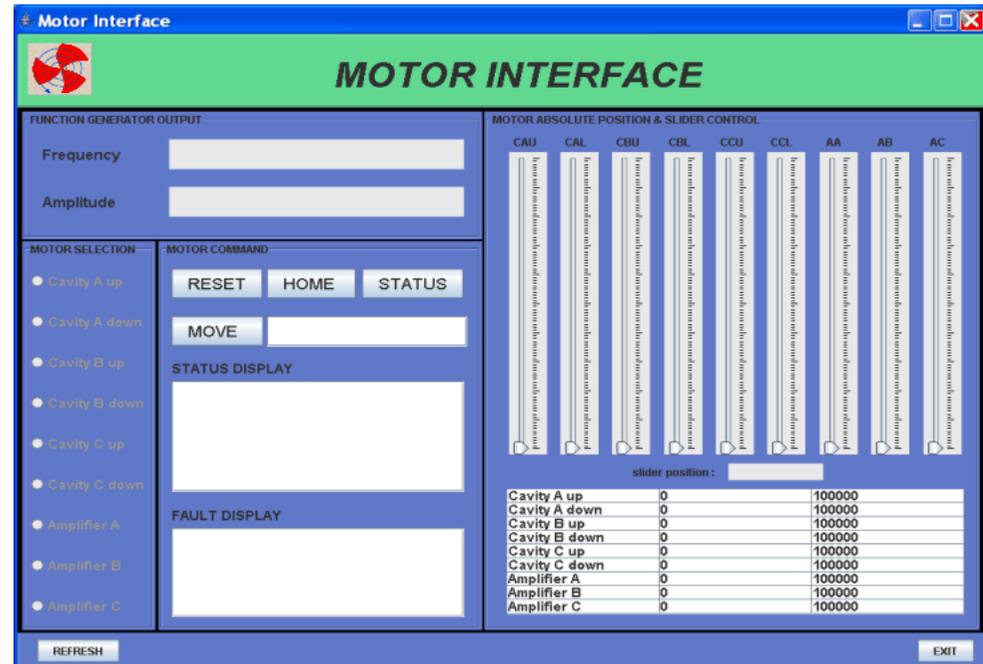
Eimac 4CW 150,000E Tetrode
assembled with Blocking Capacitor

- Assembly of Screen by-pass capacitors
- 16 nos. x 10000 pF/2.5kVDC, MICA capacitors from Jahre, Germany.

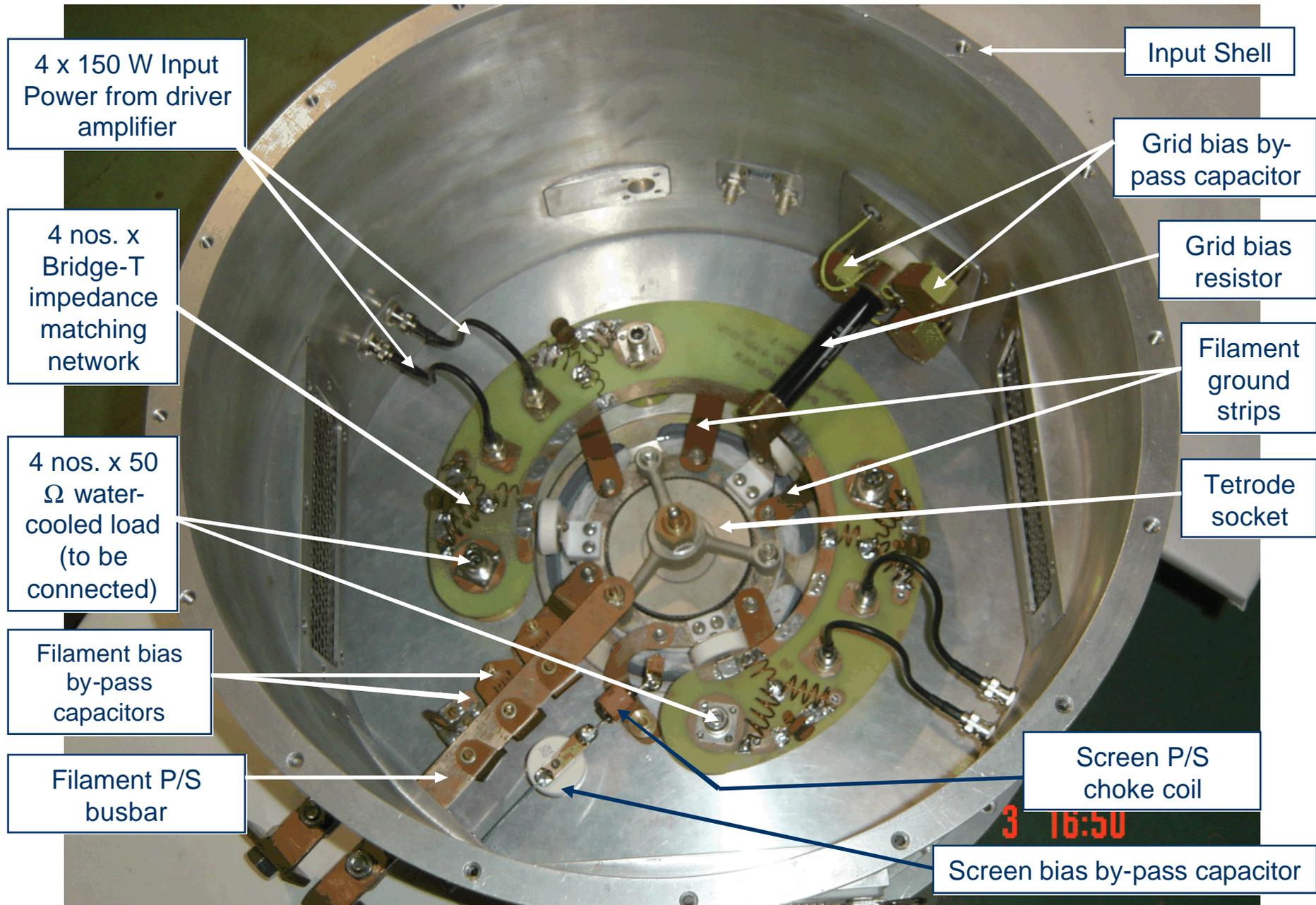


STEPPER MOTOR CONNECTION SCHEME & PC WINDOW

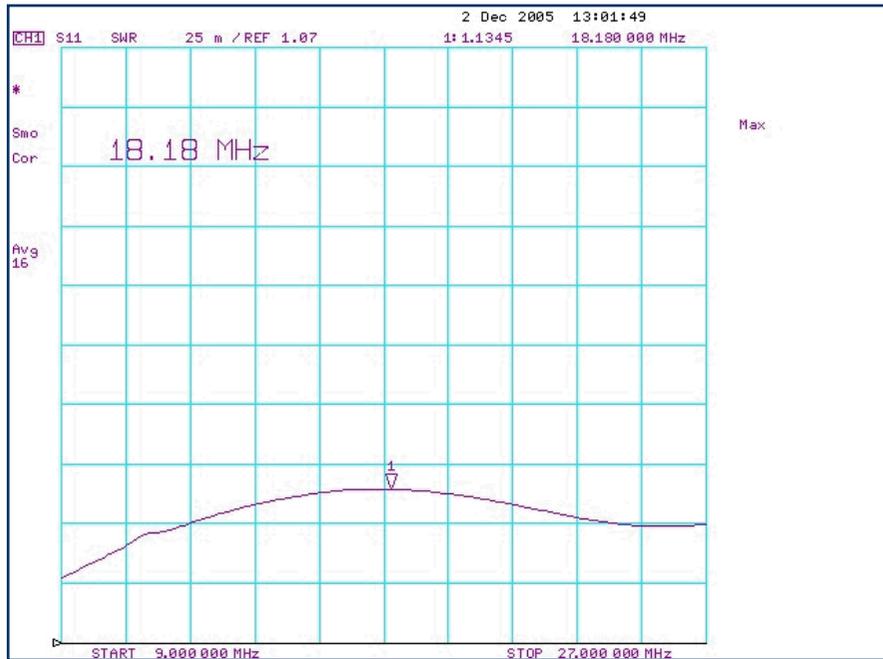
- | Motor Interface window on a PC Screen for the precise movement of sliding shorts for
 - Amplifier cavities (3 nos.)
 - Main Dee cavities (6 nos.)
- | Positioning of the stepper motor is controlled through LAN from remote computer terminal located at RF Local Control Room.
- | Indexer/Driver of the stepper motor has RS-232 interface. A RS-232 to LAN converter is used for remote operation.
- | RS-232 to LAN converter and Indexer/Driver are programmed.
- | The program is done using JAVA and MySQL.



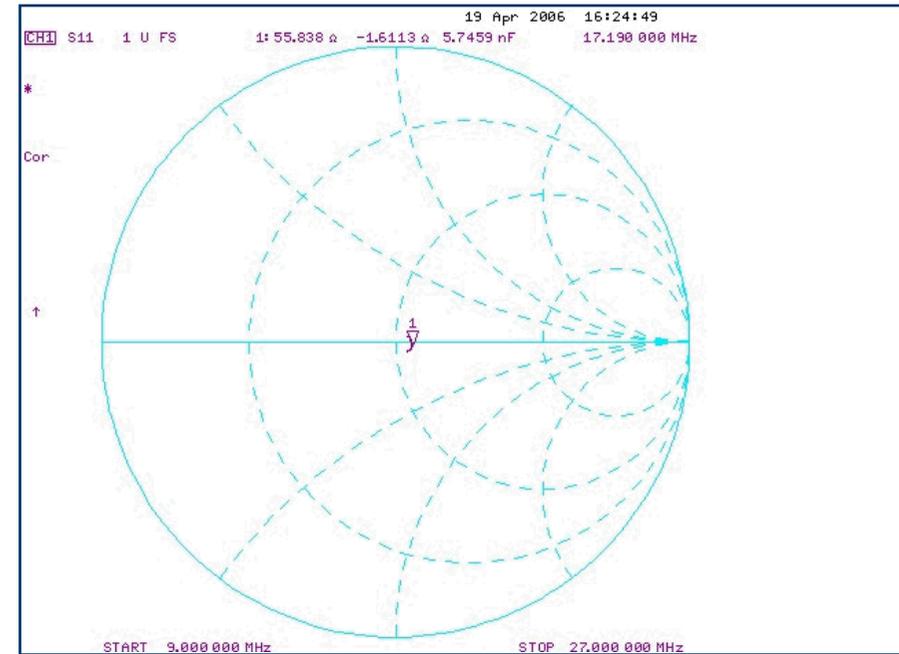
INPUT CIRCUIT FOR RF AMPLIFIER



INPUT VSWR MEASUREMENT USING VNA



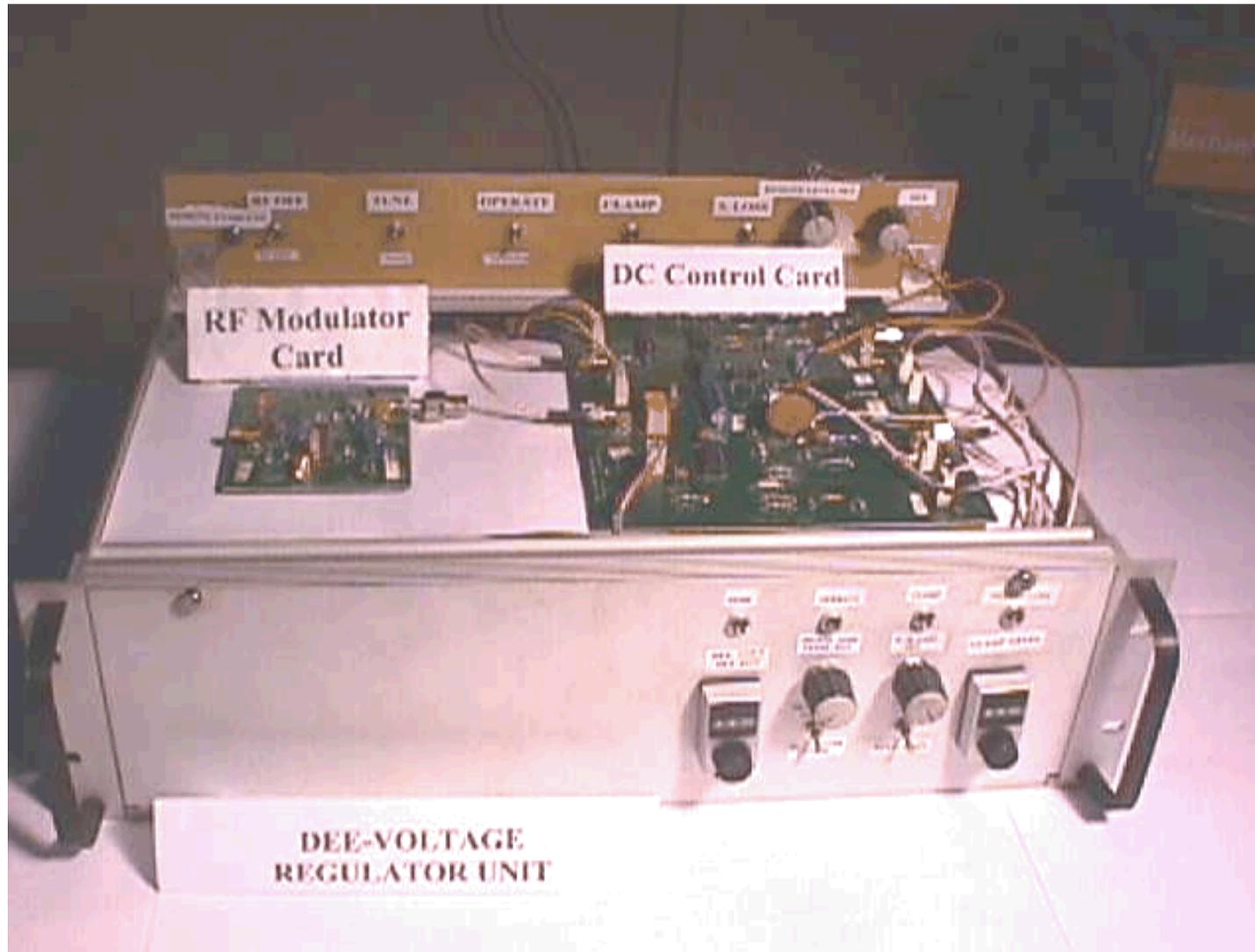
SWR format



Smith-chart format

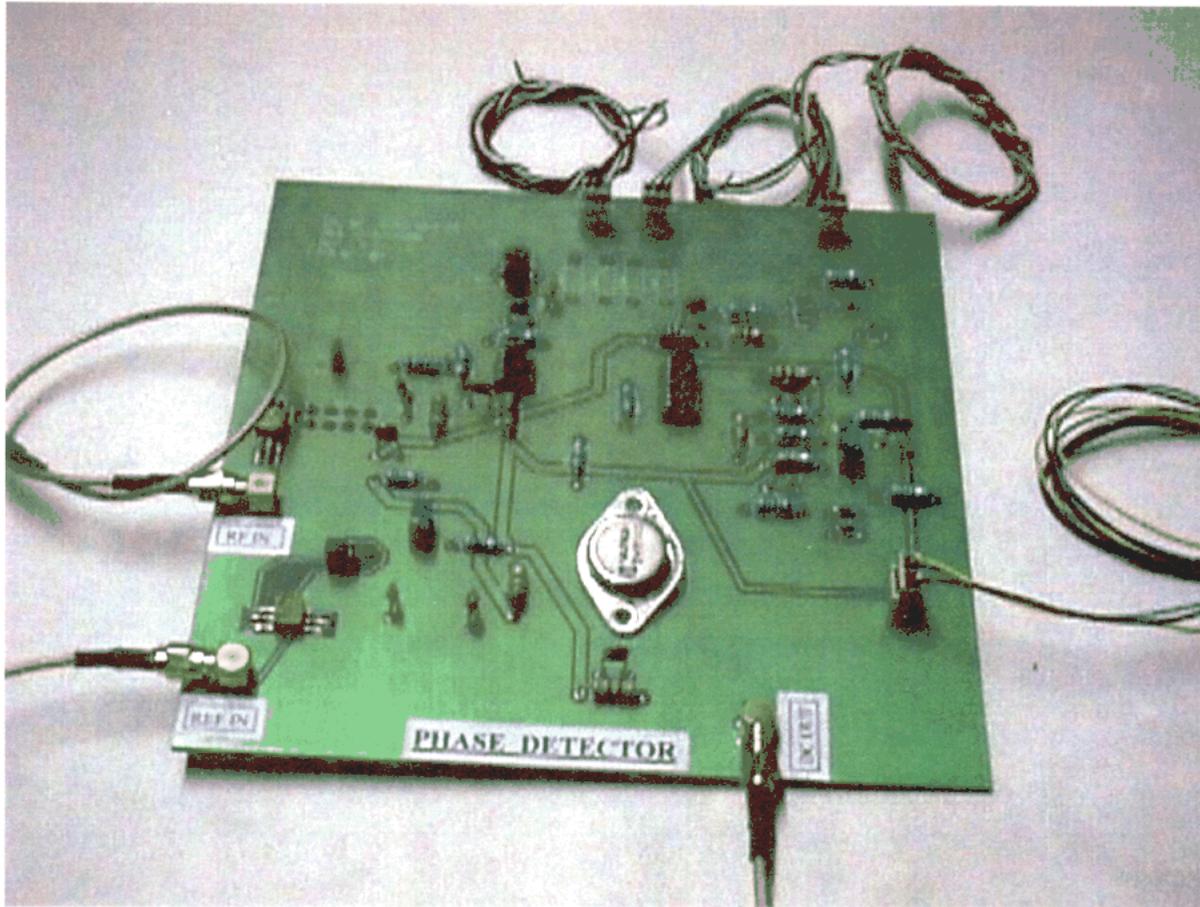
- VSWR (Voltage standing wave ratio) is measured within 9 to 27 MHz.
- Max. VSWR is 1.1345 at 18.18 MHz.
- Input impedance is $(55.838 - j1.6113) \Omega$ at 17.19 MHz

DEE VOLTAGE REGULATOR UNIT



- Based on AD834JN RF Modulator
- It modulates RF drive signal according to the error signal between highly stable dc reference and the feedback sample obtained from Dee pick-up signal
- **Dee voltage stability: 1×10^{-4}**

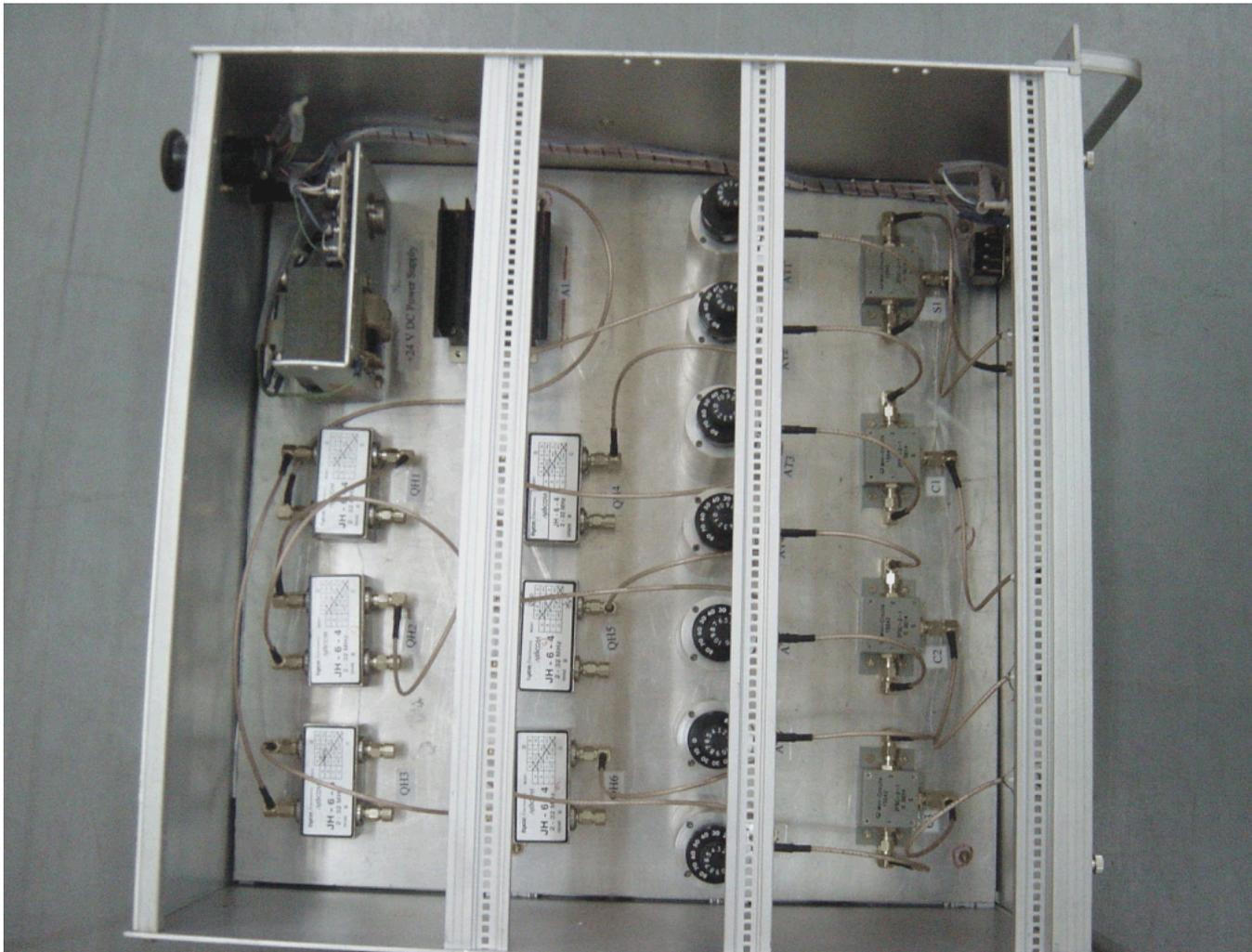
PHASE DETECTOR CARD



Phase Detector card (assembled)

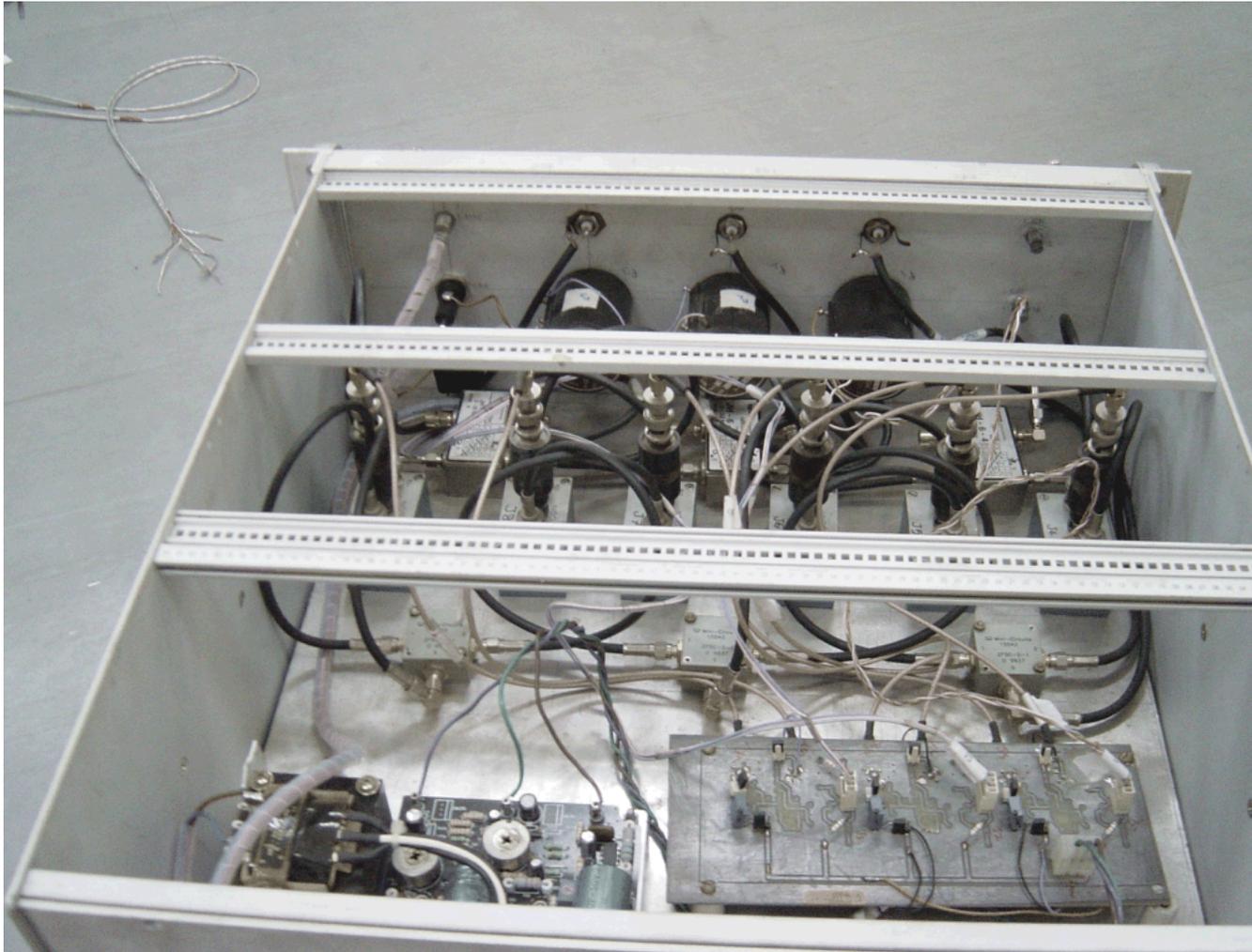
- Any deviation from sample phase from the reference phase is detected by the phase detector that produces dc error signal
- Based on double balanced mixer (used Mini Circuits# MCL-RPD-1)
- Response: 8mV/degree in +8dBm saturated mode

THREE PHASE GENERATOR UNIT



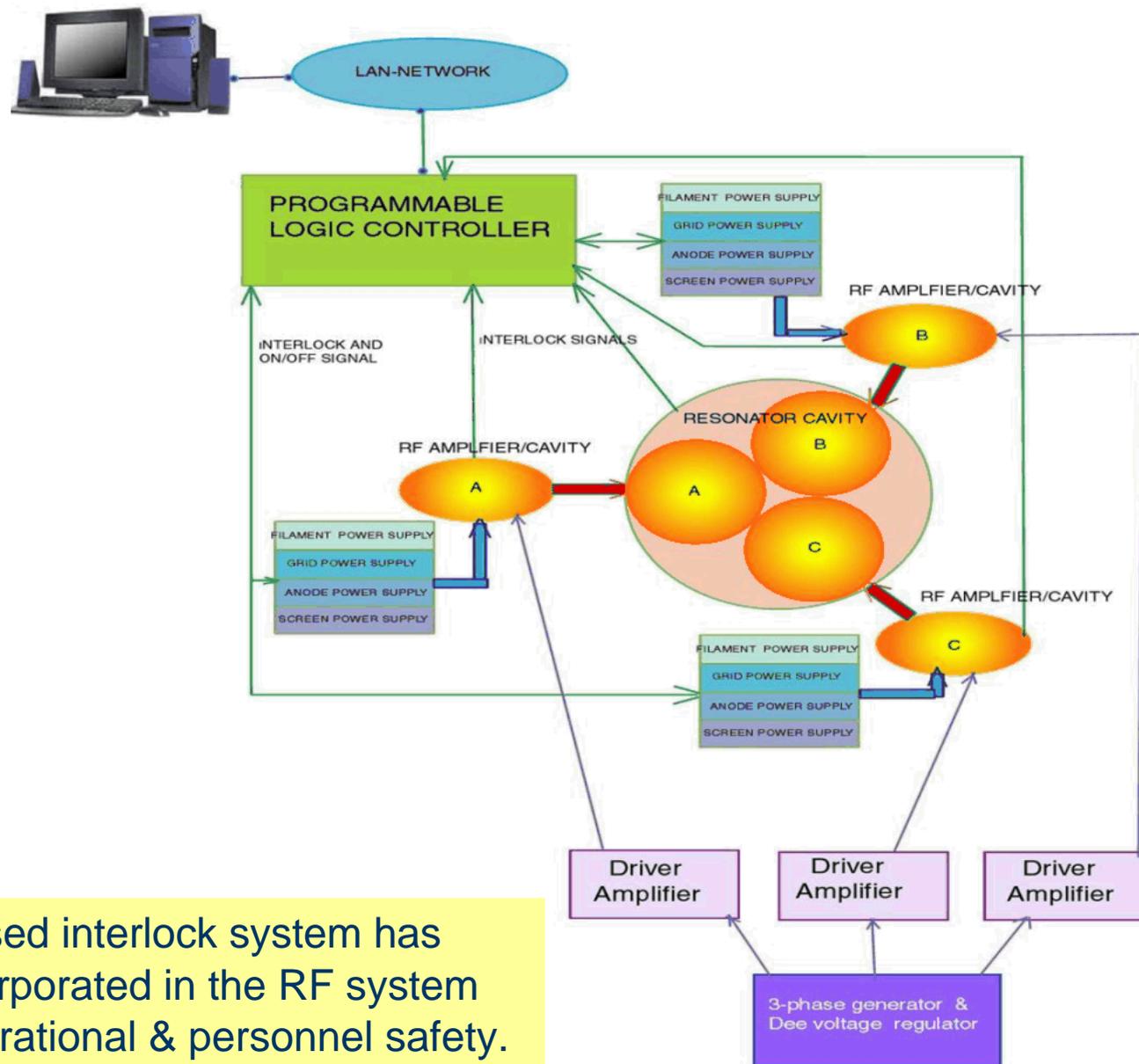
- Phase shifting of 120° is done by double mixing and auxiliary transmission line based technique, thereby making insensitive to frequency change
- Phase imbalance between 3 channels is $< \pm 1^\circ$ and amplitude unbalance is $< \pm 0.2$ dB with harmonic content < -40 dBc.

MANUAL PHASE SHIFTER UNIT



- Based on classical I&Q modulator
- Used Quadrature Hybrid (M/A COM# QH-6-4), Electronic attenuator (Minicircuits# MCL-ZAS-3) & Splitter (Minicircuits# MCL-ZFSC-2-1)
- In normal operation $\pm 15^\circ$ phase variation is sufficient and output signal balance is $\ll \pm 0.05$ dB with harmonic content less than -38 dBc

PLC-BASED INTERLOCK SYSTEM



- PLC-based interlock system has been incorporated in the RF system for its operational & personnel safety.

RF CONTROL CONSOLE



FILAMENT POWER SUPPLY



- 3 Nos. of Filament P/S.
- Rating: $15.5 \text{ V} \pm 0.75$ @ 215A DC P/S.
- Motorized Variac regulated in Primary side of 3 ϕ main power transformer.
- Slow-start feature incorporated.

CONTROL GRID POWER SUPPLY



- 3 Nos. of Control Grid P/S.
- Rating: -200V to -500V @ 100mA DC P/S
- Regulation: 100ppm & Ripple ~10mVp-p
- Regulation achieved by using IGBT (1200V, 20A) in emitter follower configuration.

ANODE POWER SUPPLY



- 1 No. of 20 kV @ 22.5A DC P/S with 3 Nos. of decoupled O/P to the anodes of 3 RF Amplifiers.
- Regulation: 6.8% with ripple ~ 50Vp-p
- Ignitron based fast Crow-bar Protection within 2mS.

SCREEN GRID POWER SUPPLY



- 3 Nos. of P/S: 1.6 kV @ 0.5A,
- Regulation: 60ppm & Ripple ~ 160mVp-p
- Fast Crow-bar protection

PRESENT STATUS

- | **Installation of all three High Power RF amplifiers have been completed.**
- | **LLRF (Low-level RF) Electronic control units for the Superconducting Cyclotron have been completed.**
- | **PC-based Stepper Motor Controlled (Sliding-Short movement) system for amplifier cavities and main Dee cavities has been completed.**
- | **PLC-based interlock system for the operational and personnel safety of the rf system has been installed.**
- | **DC Power supplies for High power rf amplifiers have been installed.**
- | **Mechanical assembly of the lower-half of three main Dee cavities have been completed and assembly of the upper-half of main Dee cavities are in progress.**

**Thank you
for your attention.**