

Design of a Treatment Control System for a Proton Therapy System

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TUOAFI02

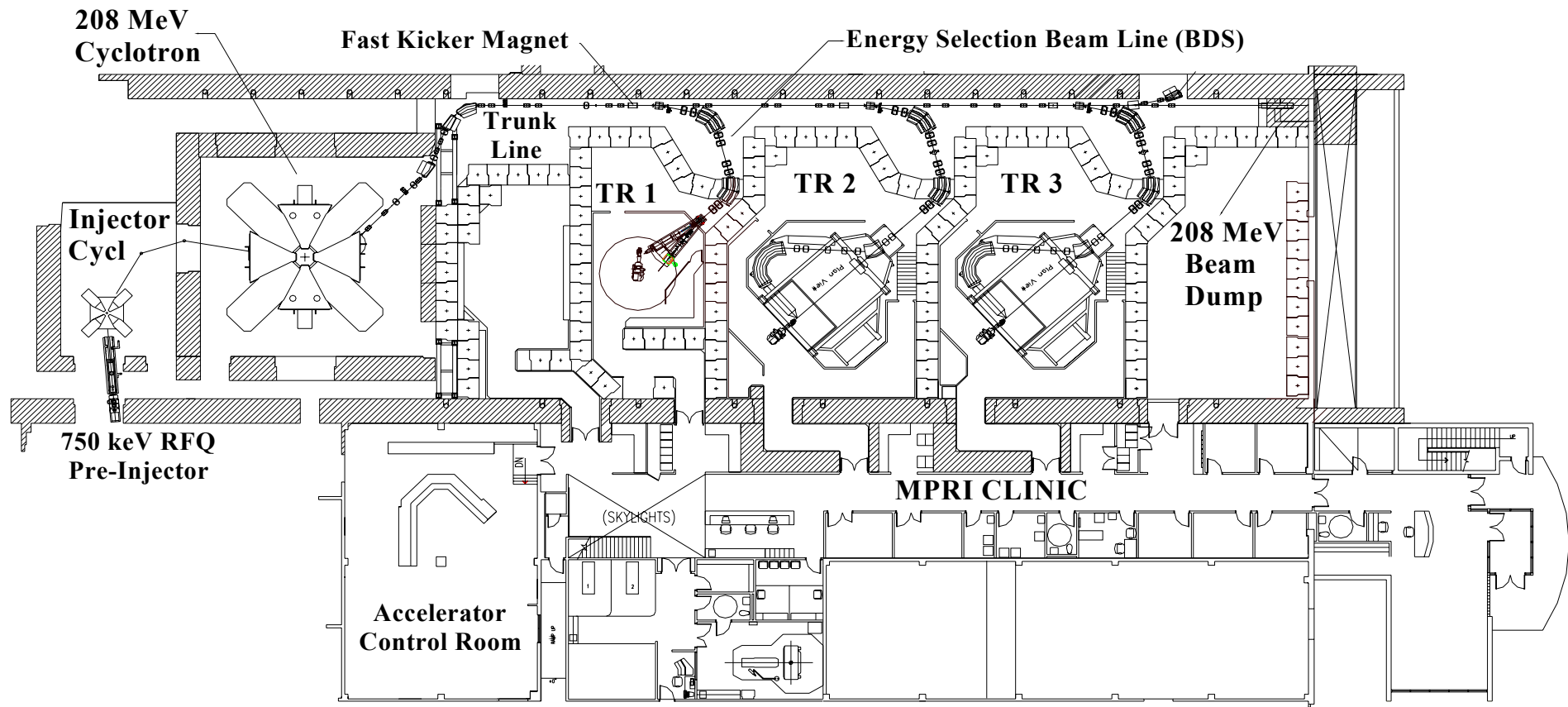
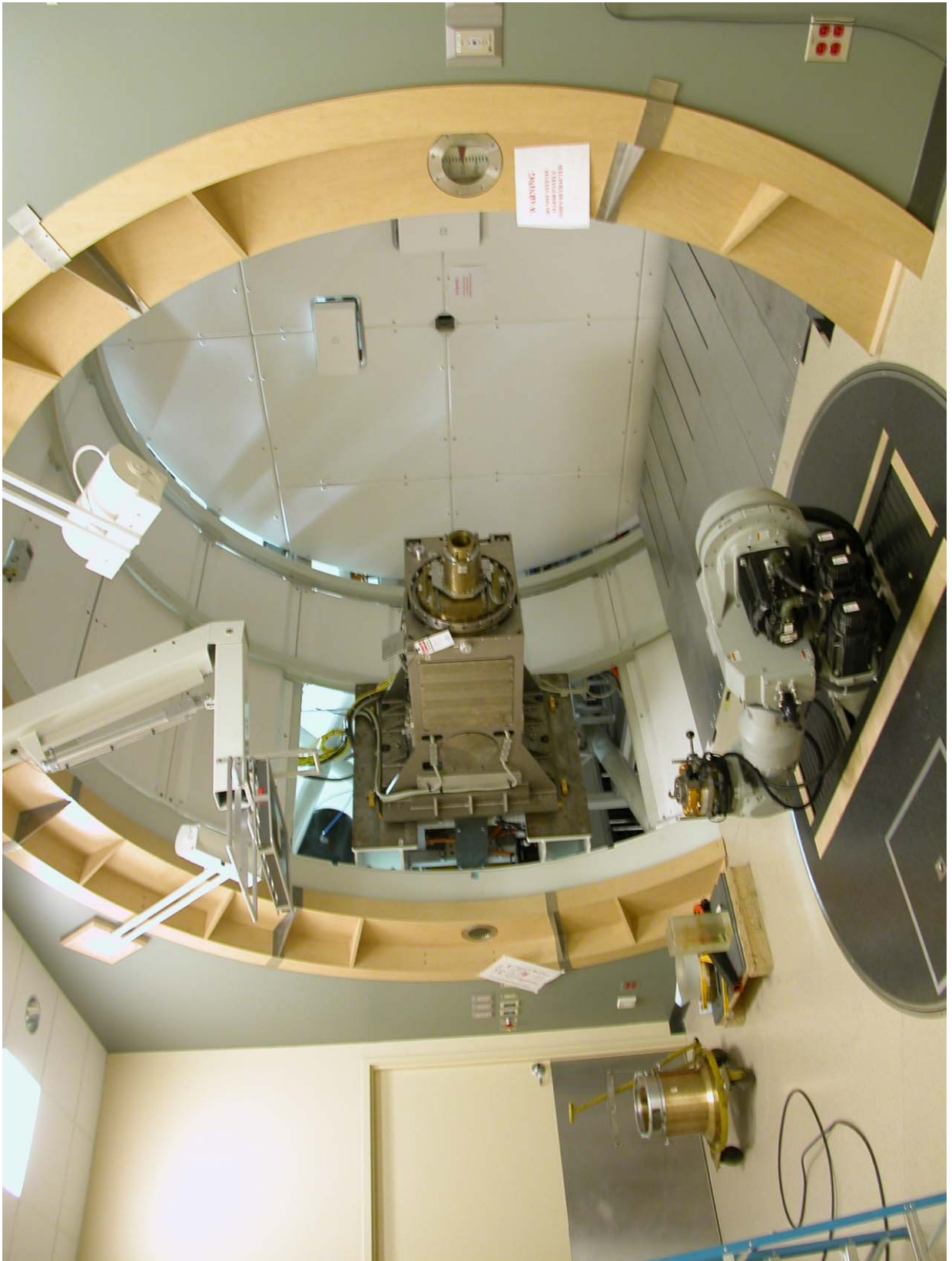


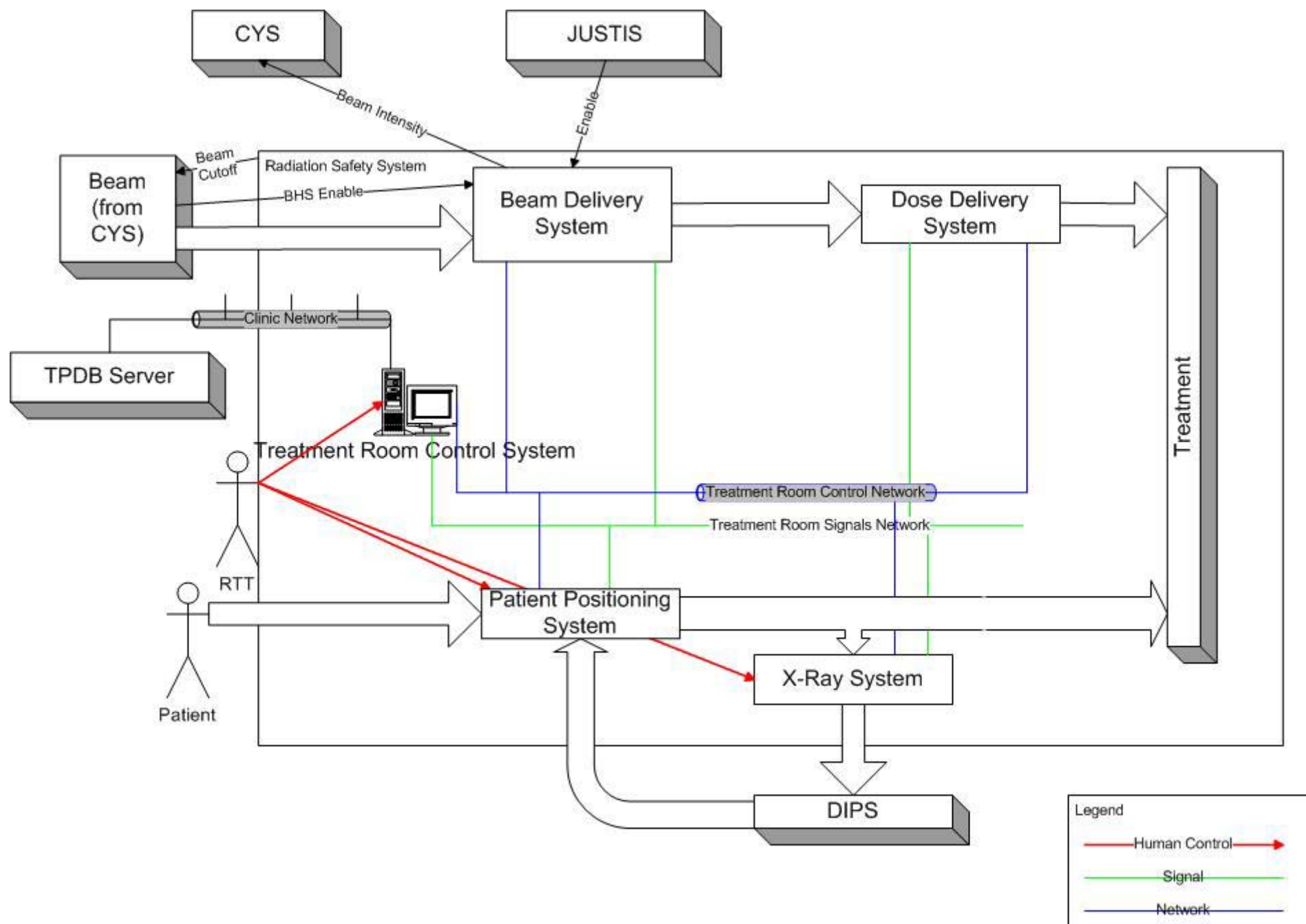
Figure 1. The MPRI facility showing the IUCF Cyclotrons, Trunk and ES lines, Treatment Rooms and Clinic.

WEPOCH179 D. Friesel, et al., The Indiana University Proton Therapy System



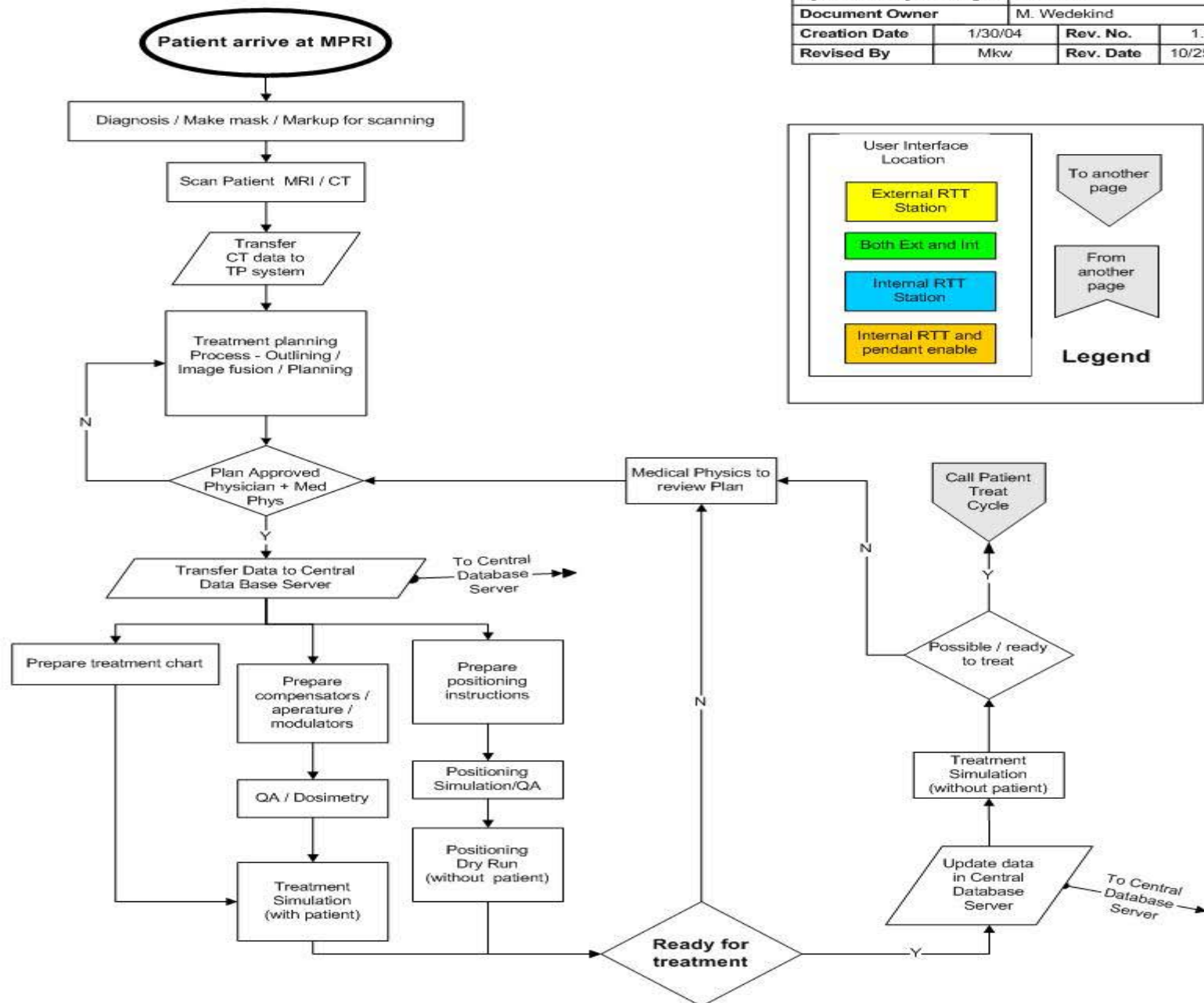
Partition System Functions

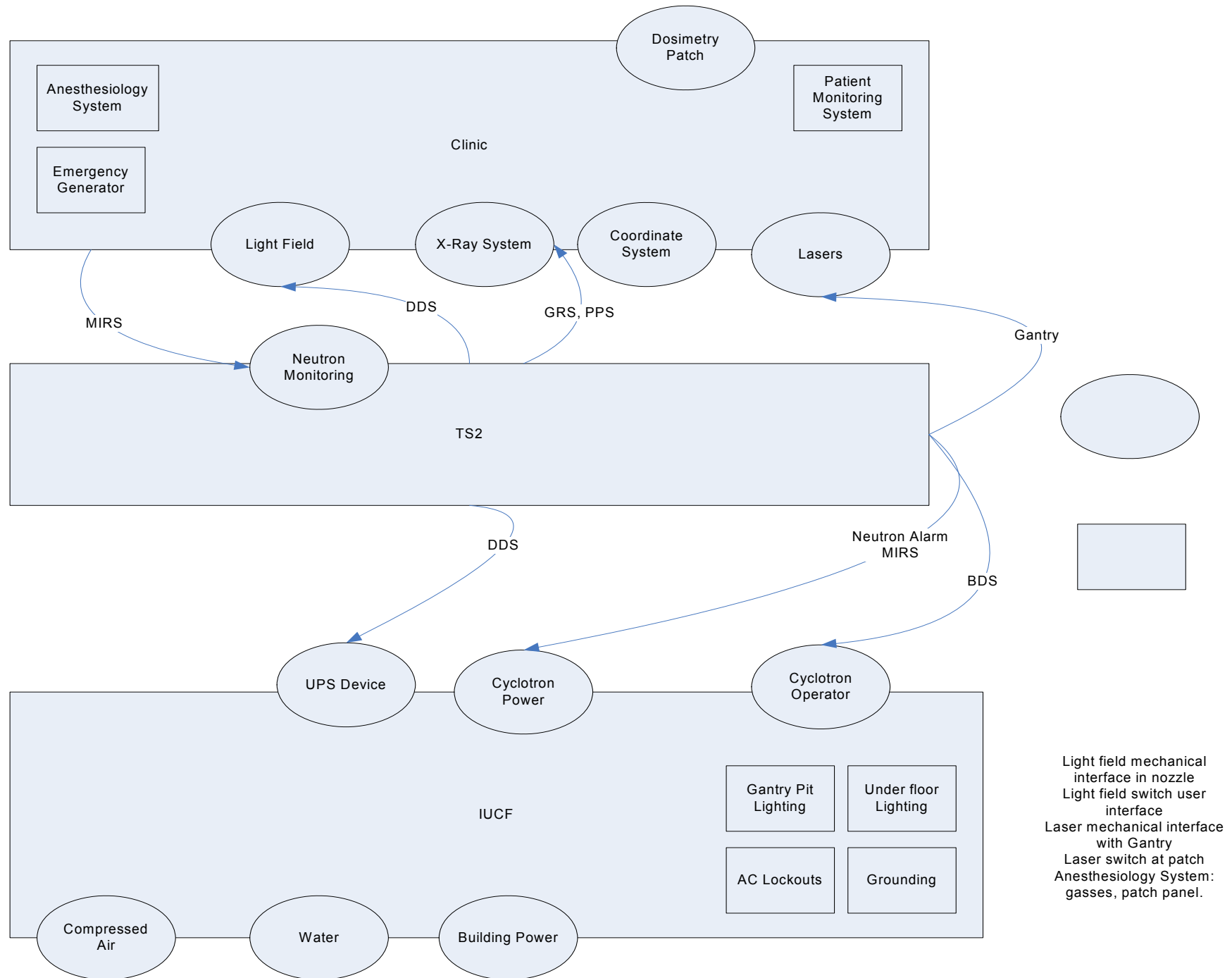
- Beam line control
 - Mimic cyclotron controls
- Dose measurement
 - Realtime measurements and response
- Patient positioning
 - X-Ray adjustment
- User interface
 - Medical data access, interpretation, distribution



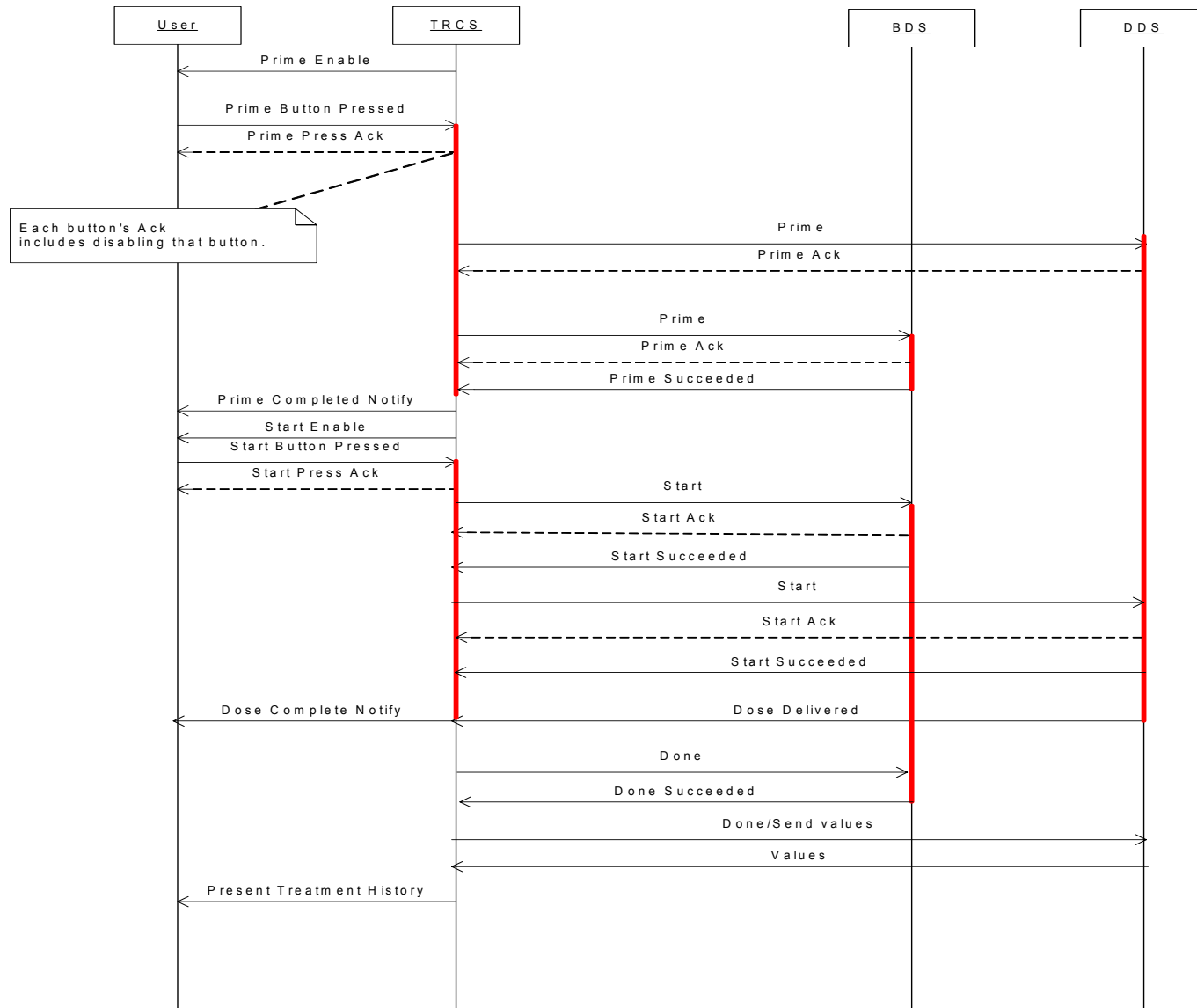
Main Patient Therapy Flow Chart

 Indiana University Cyclotron Facility			
Document Title	TS2 Treatment Process Flow		
Document Number	100421		
System/Subsys Manager	D. Friesel		
Document Owner	M. Wedekind		
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Revised By	Mkw	Rev. Date	10/25/04





Prime/Start/Done Communication Sequence



— KES Enabled

- Decide on distributed system
 - Allows use of different operating systems, platforms.
 - Allows separate development rates.
 - Requires well defined set of interfaces.

Major Systems (Software)

BDS – Set and monitor all beam line devices

Vsystem, C, OpenVMS

DDS – Monitor dose delivery

C, QNX

PPS – Set patient position

Robot DLL, C#(.Net), Windows

TRCS – Coordinate treatment process

C++, (Why not) Linux (?)

Minor Systems (No Software)

MIRS - Radiation Safety

KES – Kicker Enable

ESS – Emergency Stop

Network Communication

- TCP/IP + Ethernet
- XML-based message protocol
 - System independent
 - Schema checking
 - Existing software packages
- Receiver required to check ranges of all input parameters.

Messaging Details

- No message echo.
- Messages are entirely ASCII text.
- Expect immediate reply within a timeout (empirically determined).
- Define (delayed) replies to commands that initiate “long” processes.
- Allow asynchronous (error) messages.

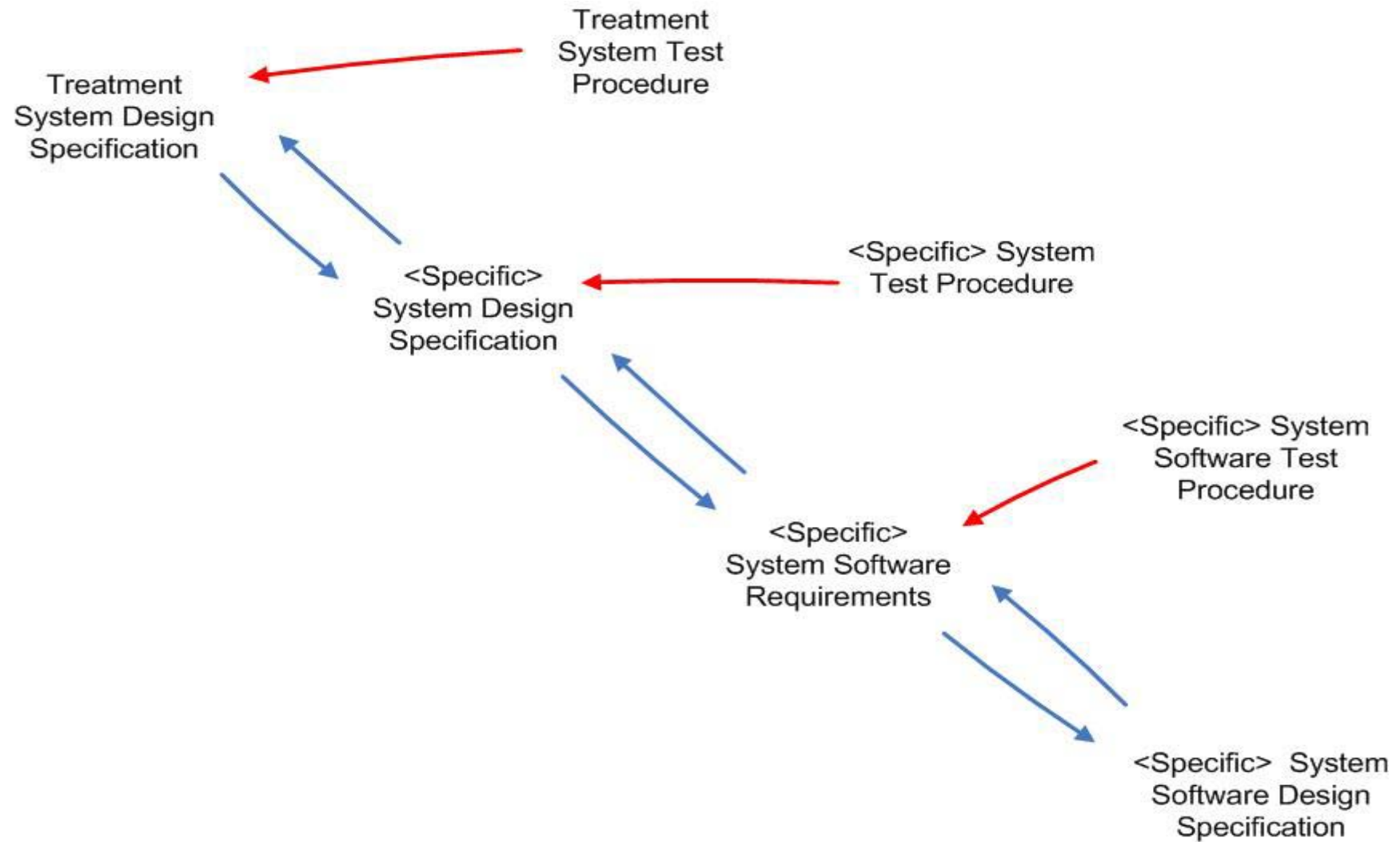
Testing

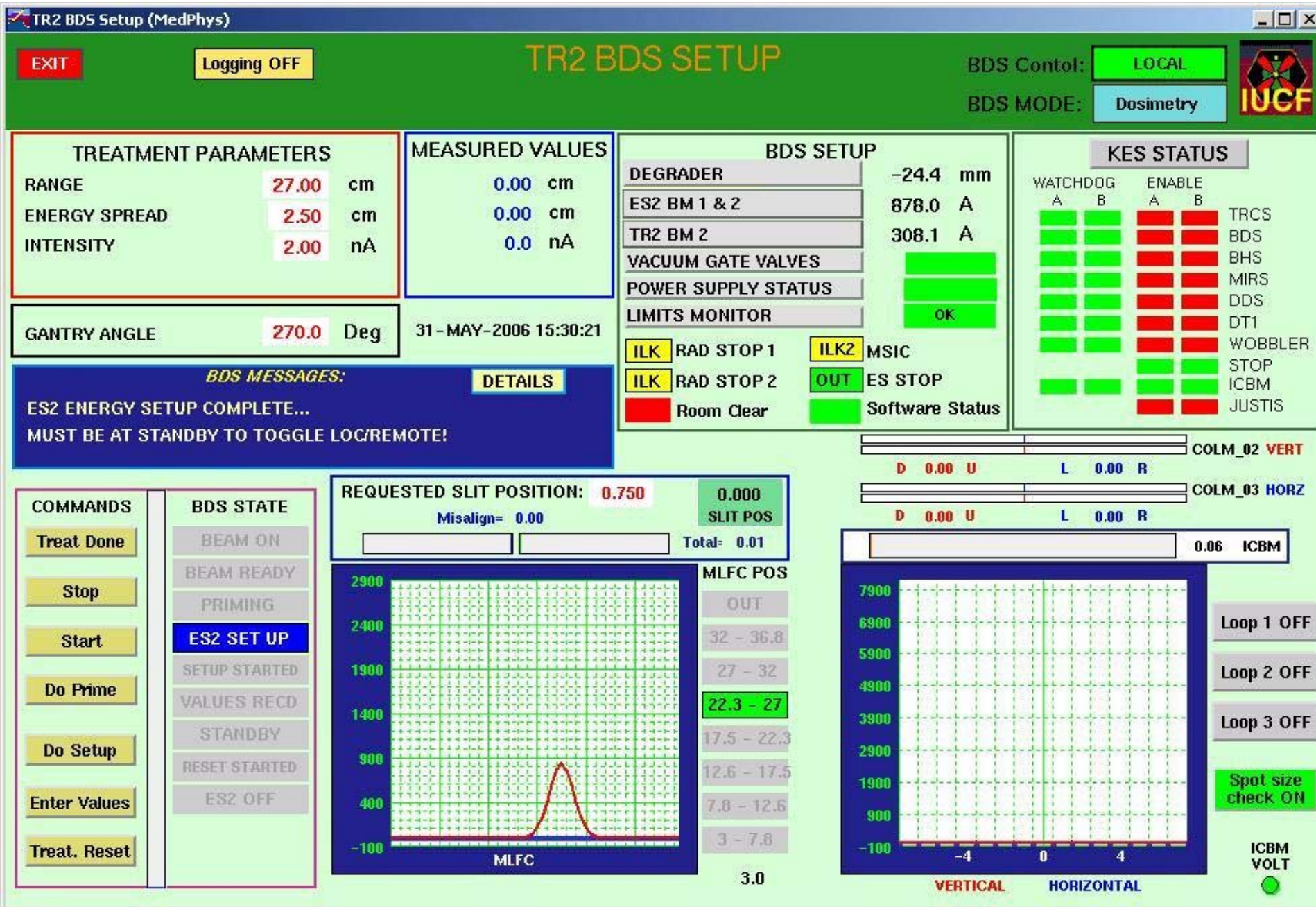
- Code review
- Unit testing
- Integration testing
- Formal Software Test
- Formal System Test

In all cases

- Happy path, Sad path
- Isolation = emulation, NePTUNE
- Time is ALWAYS underestimated

Testing





Treatment Mode

Patient Info

Patient Id: P901901

June 08, 2006

Treatment Plan: charlieplan Schema: charlieschema

Field: FINAL01 Gantry: 315.0 12:49:30

Positions

HOME

BEDDOCK

INTERMED

SETUP

FINAL01

FINAL02



Start Job



Servo Off



Teach Mode



Save Corrections



Reset



XRC Connected



Remote Mode

Robot Coordinates

X [cm]

-10.00X Θ [°]**0.0**

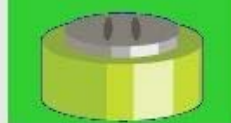
Y [cm]

172.30Y Θ [°]**0.0**

Z [cm]

-85.00Z Θ [°]**180.0**

Snout

RETRACTED

Retract Extend

DR Panels

Beamline: **Retracted**

Retract Extend

G90:

Retracted

Retract Extend

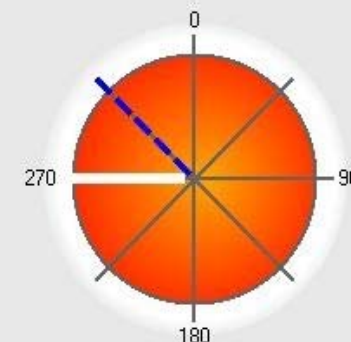
GAxis:

Retracted

Jog Control

 Δ X [cm] 0.00 Δ Y [cm] 0.00 Δ Z [cm] 0.00 Δ X Θ [°] 0.0 Δ Y Θ [°] 0.0 Δ Z Θ [°] 0.0

Gantry Angle

Current [°] **270.0**Override [°] **315.0**

ROTATE

Docking Station

LOCKED

GURNEY ID: #1

UNLOCK LOCK

Tool Changer

PNEUMATICS **ATTACHED**MECH. LOCK **LOCKED**

PSD: #14

DETACH ATTACH

DIPS **USER1**

Read From DIPS

JOG

MCP: None

OneCycle, Teach

Mode: DOSIM

DDS Monitor

State: RESET

Main DMCReg Ringver

Field Parameters (Rx)

Total Dose: 0.0 MU
 Partial Dose: 0.0 MU
 Duration: 0.00 min
 Range: 0.0 cm H2O
 SOBP Ext: 0.0 cm H2O
 SOBP Skew: 0.00

Dose Measurement

Enabled
 Error
 Disabled

DMC1 DMC2

Total Delivered MU: 0.0 0.0
 Total Duration (Min): 0.00 0.00
 MU Rate (MU/Min): 0.0

MU Difference
 Duration Difference
 DMC1-2: 0.0 % 0.00 Min

DMC Control

Clear
 Latch
 Release

State Control

Reset
 Values
 Setup
 Prime
 Start
 Stop
 Done

Energy Stacking

Active Rx

Layer: 1 0
 MU 1: 0.0 0.0
 MU 2: 0.0 0.0
 Duration: 0.00 0.00

Range Modulator
 Thick Thin
 in Out Moving

File: View E-Stack Tables

Wobbling

Size (cm)
 X: 0.0 Y: 0.0
 File:
 View Wobbler Data
 Wobbling Active:  

Calibrations

Ambient Daily OK
 Temp (C): 22.0 22.0 
 Press (hPa): 998.1 998.0 
 Correction Factor: 1.023
 Date & Time: 9/20/2005 10:05
 T-P Control (Master Values)

DMC Correction

PCI C/Volt

DMC1: 0.000 0.000
 DMC2: 0.000 0.000

PDM High Voltage

Monitor Feedback:

HV1: 1487.0 1499.8 
 HV2: 1478.7 1504.7 

XRay Tube

In/Out 
 Jaw Widths (cm)
 Request Actual OK
 X: 0.0 0.0 
 Y: 0.0 0.0 
 Stop Jaws

Device Status Info

 Aperture In Place
 Compensator In Place
 PDM In Place
 Snout Locking Ring:
 Snout Rotation Lock:
 XRay Drive Press:
 Range Mod Pressure:
 Cradle Temp

Snout

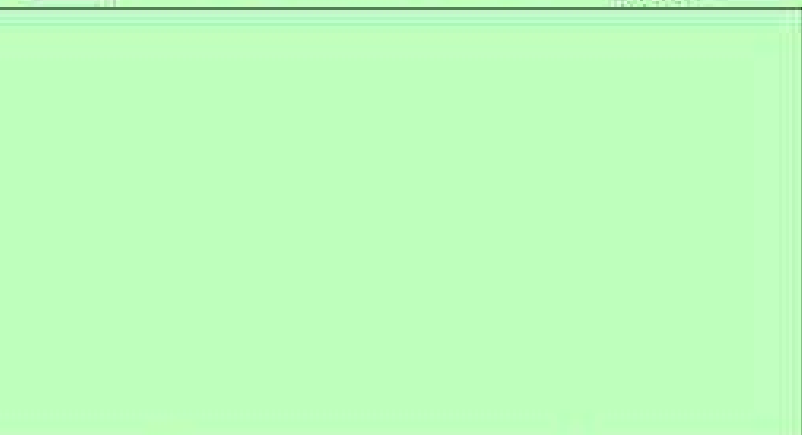
Request Actual

ID: 0 10 
 Position (from IsoCenter): 52.5 52.5 
 Angle: 0.0 0.0 
 Stop Snout

Accum

Patient Dose Monitor

Display Scale: 10000



Cent: -15.50 Flat: 0.00 Cent: -15.50 Flat: 0.00
 Bal: 0.00 Sym: 0.00 Bal: 0.00 Sym: 0.00

Error Message

Timestamp

9/20/05 10:05

Acknowledge

