

Quadrupole MPS

The quadrupole magnet power supply prototype 250 A/40 V main circuit uses two modules in parallel, of which each module 125 A/40 V consists of rectification and high frequency DC/DC converter. There are 2 designs on the structure. The first solution uses a standard 4U chassis and is water cooled. The second solution uses two 19-inch 1U modules stacked, and the power circuit uses silicon carbide devices for air cooling. The principle block diagram of the two schemes is shown in Figure 2. Both prototype control schemes are digital plus analog control. The voltage loop and current sharing loop of the core adopt analog adjustment, which can improve the speed of the inner loop, facilitate peak current control and reduce voltage ripple [6]. The digital current outer loop avoids the effects of analog control temperature drift and device aging, and can be adjusted by software. And optimizing the parameters of the control loop ensures that the accuracy of the power supply reaches 10 ppm. At the same time, the feedback loop adopts precise temperature control. The ADC operating temperature is controlled at $\pm 0.5\text{ }^{\circ}\text{C}$ to reduce the temperature of the power supply. The input and output filters use a common-mode filter to reduce the noise of the system. Key chips such as ADCs and DACs communicate with the CPU through digital isolators to ensure minimal interference to the system.

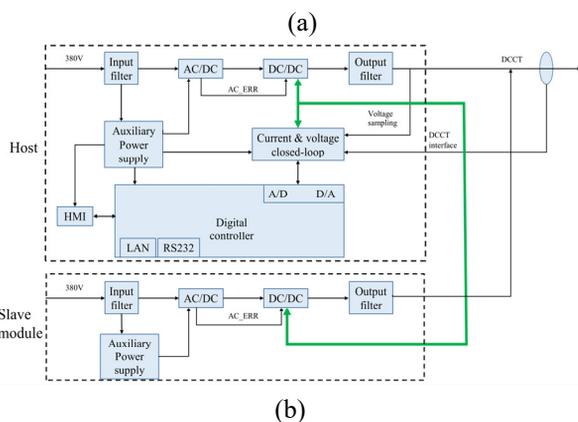
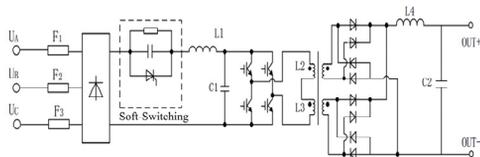


Figure 2: Block diagram of the two schemes. (a) Using 4U module. (b) Using 1U module.

Fast-response MPS

The fast response power supply provides excitation current for the fast-track feedback corrector magnet, requiring fast response. At the beginning of the power supply design,

through research, taking into account the power supply bandwidth, current ripple and other technical indicators, decided to use switching power supply and linear power supply two topologies to develop separately to ensure the realization of engineering indicators [7-8]. At present, the first version of the self-designed digital linear power principle prototype has been completed. The core of the power supply is the high-precision analog given chip AD5791, which has a 20-bit resolution and can meet the design target's current setting resolution better than 20 ppm. The controller uses the ARM core STM32 integrated circuit chip to replace the conventional DSP, because the linear power supply does not require the high resolution mode PWM function, the power control does not require modules such as hardware multipliers, the STM32 has low power consumption characteristics and rich the control interface is more suitable for development. The voltage and current double closed-loop control strategy is adopted to ensure the stability meets the basic requirements. The first version of the control unit is equipped with the RJ45 interface to interface with the communication protocol provided by the control group. At the same time, the HMI based on the touch screen is developed to facilitate local control and debugging. The block diagram is shown in Figure 3.

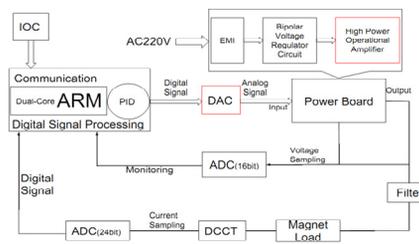


Figure 3: Block diagram of the fast-response power supply.

PROTOTYPE AND TEST RESULTS

The digital controller is the core component of the power supply, and mainly implements the realization of the power control algorithm, the generation of the PWM, the control of the feedback channel ADC and its conditioning circuit, and the functions of remote communication. The ultra-high stability digital regulator has completed the first version of the design and processing, and the controller adopts the interface form of the core board plus the sampling board plus the power board and the back board. Figure 4 shows the physical map of the digital control card.



Figure 4: The digital control card.

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This controller has been applied to a small power supply of ± 10 A/12 V and has a long-term stability of 20 ppm at room temperature. The test results are shown in Figure 5.

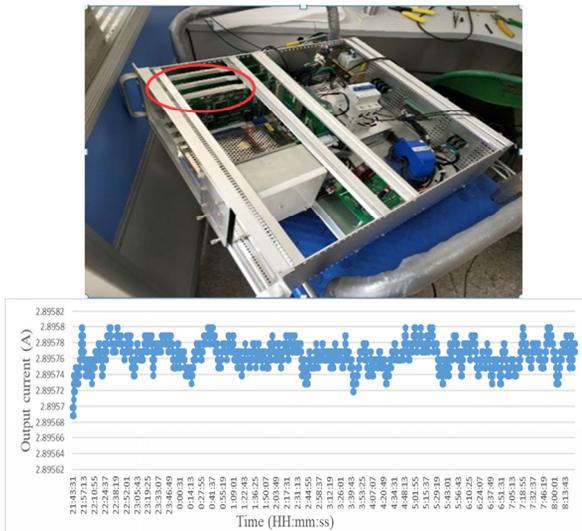


Figure 5: Stability test of the first version of the digital control card.

The prototype of the first version of the digital linear power supply uses the topology of the audio power amplifier circuit, so the frequency response can fully meet the requirements, and the 10 kHz sine wave can respond. Input and output delay is also less than 100 μ s. Figure 6 shows the test results.

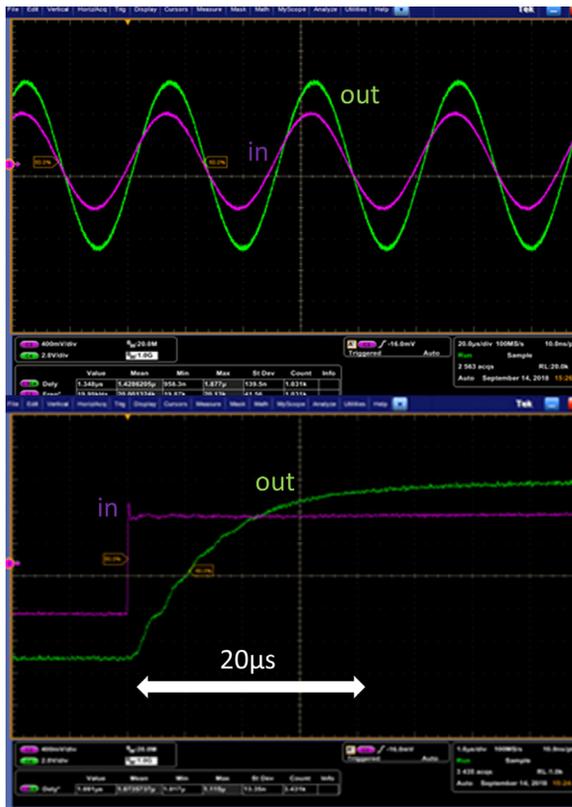


Figure 6: Frequency response test results of digital linear power supply.

CONCLUSION

At present, the HALS power supply system is progressing smoothly, and the prototype can basically reach the target. The first version of the high stability power supply has a test stability of 20 ppm. The test environment has a certain impact on the results. If we add constant temperature control, the results should be better. The fast response power supply uses a linear power supply scheme with a frequency response of 10 kHz and a rise time of 20 μ s. The power loss of the linear power supply is too large, mainly due to the characteristics of the linear amplifier component operating in the linear amplification region. Using a large heat sink can take away heat, but efficiency is a problem to consider in the future. The future research focus of digital control card should be on A/D sampling constant temperature processing and algorithm optimization.

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